

~~SECRET~~/STIPPLED/NOFORN/WNINTEL  
SPECIAL ACCESS REQUIRED

PROJECT SUN STREAK

WARNING NOTICE: INTELLIGENCE SOURCES AND METHODS INVOLVED

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PROJECT NUMBER: D003                      SESSION NUMBER: 01  
DATE OF SESSION: 18 SEP 9                DATE OF REPORT: 18 SEP 90  
START: 1020                                END: 100  
METHODOLOGY: SOLO                        VIEWER IDENTIFIER: 018

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1. (S/STD) MISSIONS: Determine the location of a small plastic container hidden in an agreed-upon area of search located in the immediate vicinity of Bldg T-2560 and T-2561. ERV Tgt 5240 was contained in the plastic holder

2. (S/STD) VIEWER TASKING: From an agreed-upon starting point find the target while acting in a direction finding mode.

3. (S/STD) COMMENTS: No inclemencies noted. A Summary of Information is attached to this report and reflects methodology (ies) used. [In this case, six of them.] Of the six methods used, the pendulum came closest to finding the target.

4. (S/STD) EVALUATION:

5. (S/STD) SEARCH EVALUATION:

HANDLE VIA SKEET CHANNELS ONLY

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SPECIAL ACCESS REQUIRED

CLASSIFIED BY: DCSINT (PO)  
DECLASSIFY ON: OADR

WORKING PAPER

Project: <sup>0003</sup>BF-003  
Date: 900918  
Time: 1020  
Viewer: 018

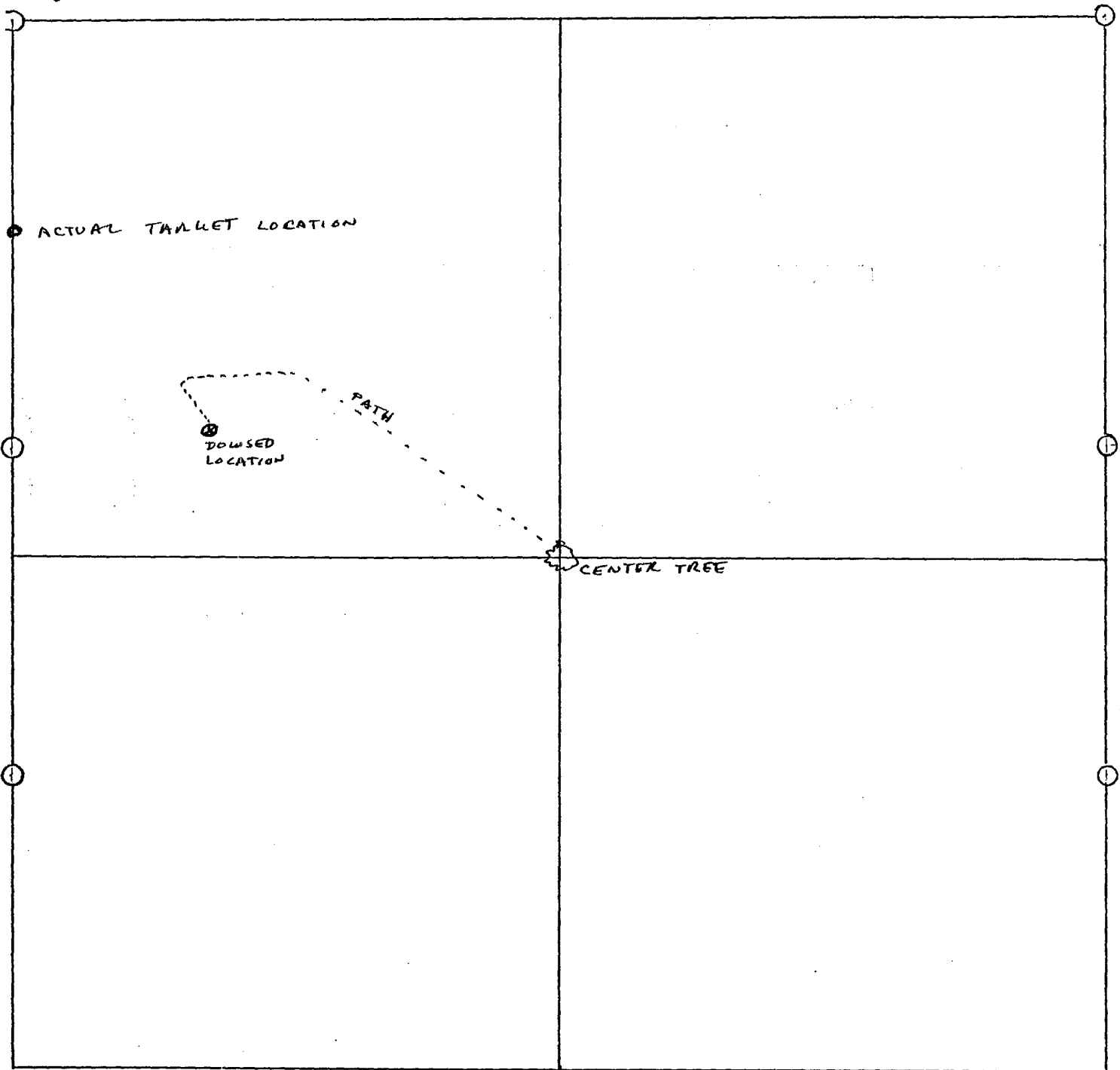
SUMMARY OF INFORMATION:

1. TASKING: Determine the location of a hidden target in a confined area of land.
2. METHODOLOGY<sup>1</sup>: I started at the "central tree" and felt for warmth from the target (the weather was very cold).
3. RESULTS: The attached map indicates the results of this method, and the path traveled as I progressed. The standard formula<sup>2</sup> for computing locational error within confined boundaries indicates this as 79.71% accuracy.

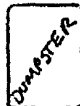
<sup>1</sup> Six different methods were used for this target, with success rates ranging from 100% accuracy (pendulum method) to 75.71% accuracy ("hot finger"). Results of these methods are kept in personal records.

<sup>2</sup> Percent accuracy is determined by the standard formula for computing locational error within confined boundaries:

$$100 * (1 - (\text{ACTUAL ERROR} / \text{MAXIMUM POSSIBLE ERROR}))$$



BLDG 2561



BLDG 2560

PARKING LOT