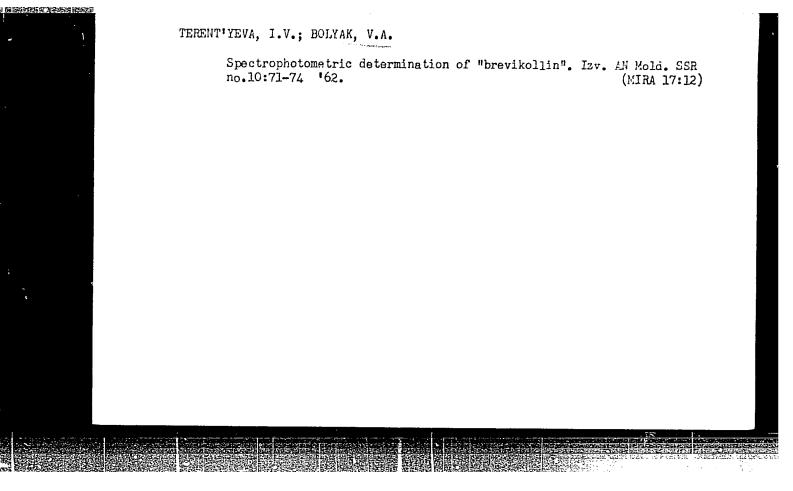


KRASIL'NIKOV, N.A.; BOLTYANSKAYA, E.V.; SOKOLOV, A.A.; MELHONYAN, Zh.

Flagelliform outgrowths in Azotobacter, Dckl. AN SECR 164 no.4:931-933 0 165. (MIRA 18:10)

1. Moskovskiy gosudarstvennyy universitet. 2. Chlen-korrespendent AN STOR (for Krasil bikov).

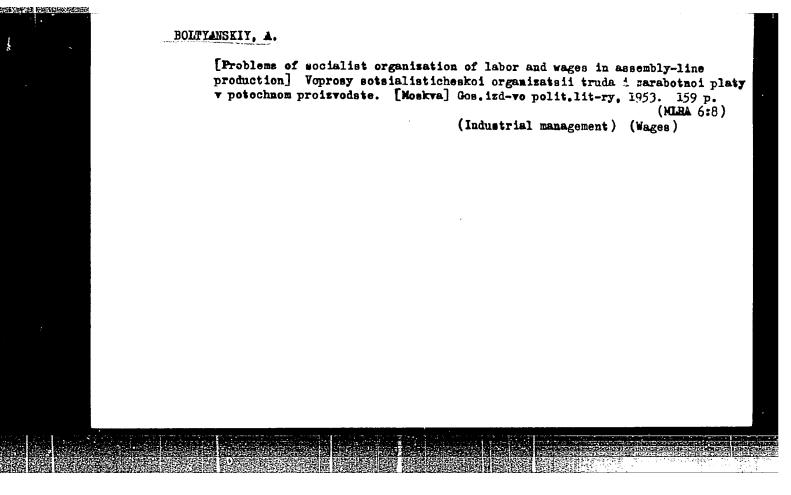


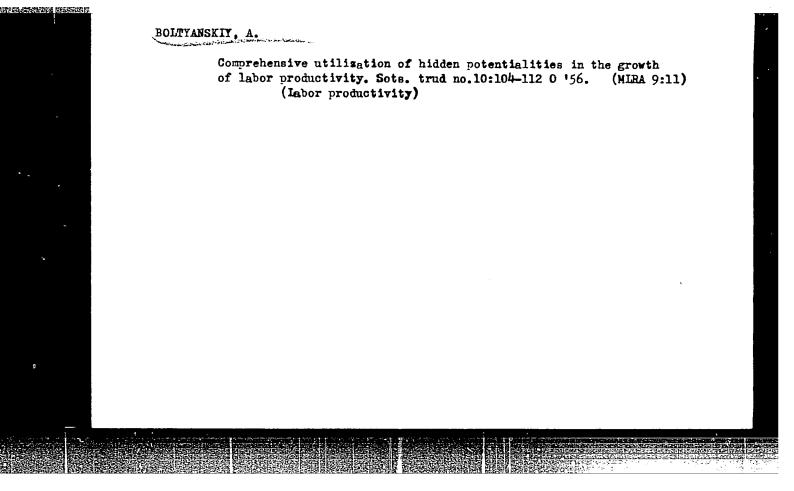
KOTEL NIKOV, Boris Pavlovich; BOLYANOVSKIY, Dmitriy Mikhaylovich; AGEYEV, P.M., red.; GONCHAROVA, Ye.A., tekhm. red.

[First in the country; story of the Shebekino Combine of Synthetic Fatty Acids and Aliphatic Alcohols] Fervyi v strane; rasskaz c Shebekinskom kombinate sinteticheskikh zhirnykh kislot i zhirnykh spirtov. Belgorod, Belgorodskoe knizhnoe iztvo, 1961. 49 p. (MIRA 15:8)

1. Direktor Shebekinskogo nauchno-issledovatel'skogo instituta sinteticheskikh zhirozameniteley i moyushchiki sredstv (for Kotel'nikov). 2. Glavnyy inzhener kombinata sinteticheskikh zhirnykh kis_pt i zhirnykh spirtov (for Bolyanovskiy).

(Shebekino--Oils and fats)





SOV-2-58-8-3/12 AUTHOR: Boltyanskiy, A. The Study of Mechanization and Automation of Industry (Ob TITLE: izuchenii mekhanizatsii i avtomatizatsii v promyshlennosti) Vestnik statistiki, 1958, Nr 8, pp 20 - 29 (USSR) PERIODICAL: Many questions on the characteristics of mechanization and ABSTRACT: automation of industrial production have not been completely worked out theoretically and are interpreted in practice in different ways. Such initial concepts as partial and complete mechanization or complex mechanization are without a definite content and clearly outlined limits. The present article examines some of these questions, taking the work in foundries of machine construction plants as an example. A proper evaluation of the engineering-economic degree of mechanization and automation can only be given provided the following four basic indices are thoroughly examined: 1) the extent of mechanization and automation of individual operations; 2) the extent of the complexity of mechanization and automation in a section, a workshop or Card 1/3

'The Study of Mechanization and Automation of Industry SOV-2-58-8-3/12

in the enterprise as a whole; 3) the engineering degree of the adopted means of mechanization and automation; 4) the effectiveness of mechanization and automation. The author quotes generally accepted definitions for stages of development of partial and complete mechanization and automation with which he does not entirely concur. He examines the difference of opinion by examples, quoting in this connection a table which shows the expenditure of time in molding one machine part. He tries to prove that an increase in the degree of mechanization and automation is accompanied by a relative augmentation of the share of manual labor if all or most of the labor-consuming operations are not simultaneously mechanized. A higher form of mechanization should be regarded as that in which basic operations are

Card 2/3

'The Study of Mechanization and Automation of Industry SOV-2-58-8-3/12

completely mechanized, and only auxiliary work is performed by hand. The lower stage of mechanization is the one where only a part of the basic operations are mechanized. Turning to the complexity of automation, the author maintains that none of the existing definitions are sufficiently clear. He illustrates this by particulars on the operation of a continuous conveyer section of a foundry. To characterize the degree of mechanization (automation) of an area, workshop or enterprise, the author suggests considering several symptoms and comments on them. Dealing with indices of effectiveness of mechanization, he states that effectiveness is not characterized by any single index but by the total of indices. There are 6 tables and 5 Soviet references.

Card 3/3

INVENTOR: Boltyanskiy, A. A.; Pshenichnikov, Yu. V.

ORG: None

TITLE: Measurement attachment to fit on an automatic machine for multiple-range sorting according to deviation of some parameter from standard. Class 42, No. 182898 [announced by the Kuybyshev Aviation Institute (Kuybyshevskiy aviatsionnyy institut)]

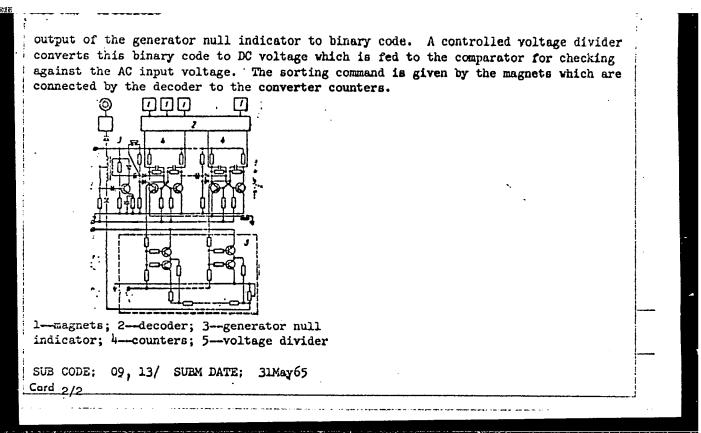
SOURCE: Izobretniya, promyshlennyye obraztsy, tovarnyye znaki, no. 12, 1966, 89

TOPIC TAGS: analog digital converter, digital analog converter, sorter, parameter

ABSTRACT: This Author's Certificate introduces a measurement attachment to fit on an automatic machine for multiple-range sorting according to deviation of some parameter from standard. The device contains an industrial-frequency induction transducer for converting this deviation to AC voltage. Measurement accuracy is improved and sorting speed is increased by equipping the instrument with magnets, a decoder and a converter with feedback which includes a device for comparing AC input voltage of industrial frequency with the output voltage of the converter. The converter also incorporates a generator null indicator connected to the output of the comparator and generating pulses if the amplitude of the AC input voltage in the comparator is greater than the output voltage of the converter. Counters convert the pulses from

Cord 1/2

UDC: 531.7:621.3.078.3



ACCESSION NR: AR4042171

8/0272/64/000/005/0024/0024

SOURCE: Ref. zh. Metrologiya i ismerit. tekhn. Otd. vy*p., Abs. 5.32.138

AUTHOR: Boltyanskiy, A. A.

TITLE: Inductive multirange meter of small displacements

CITED SOURCE: Nauchn. tr. vuzov Povolzh'ya, vy'p. 1, 1963, 180-186

TOPIC TAGS: inductive multirange meter, displacement

TRANSLATION: A differential multirange inductive pickup with linear scale (non-linearity within 2%) is described. Limits of measurements ± 30; ± 30; ±300; and ±30; ±60 and ± 300 M. Heasuring force 100-150 gs. Eight illustrations. Bibliography: 4 references.

SUB CODE: IM, IE

ENCL: 00

Card 1/1

BOLTANSKIY, A.1., kand. ekon. nauk.

Production resources of assembly line operations in foundries. Manhinostroitel' no.1:11-14 Ja '58. (MIRA 11:1)

(Foundries) (Assembly line methods)

POLTYPNSKIY N. J.

117-58-7-10/25

AUTHOR:

Boltyanskiy, A.I., Candidate of aconomic Sciences

TITLE:

Production Reserves on a Foundry Conveyer Line (Rezervy pro-

izvodstva na konveyernoy linii v liteynom tsekhe)

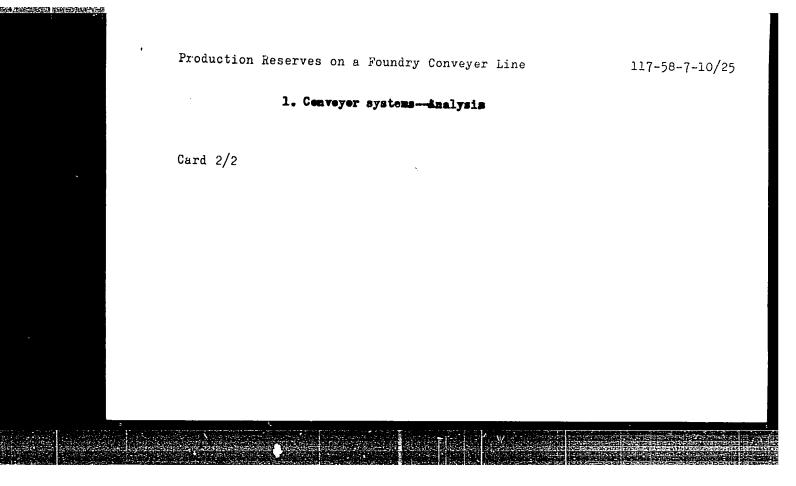
PERIODICAL:

Mashinostroitel', 1958, Nr 7, pp 30 - 32 (USSR)

ABSTRACT:

The work of the conveyer line in the grey cast iron section of the "KATEK" Plant, a foundry in Kuybyshev, is here statistically analyzed. "Bot lenecks" forming on the line are explained by incomplete mechanization. Only the preparation of molding mix is nearly fully mechanized. Of 27 different operations only 10 are mechanized, and 103 workers of the 133 working on the line are occupied by manual work which includes the pouring. The mechanization of the line is illustrated in table 3 showing the situation in 1955 and after re-mechanization in 1957. The author stresses the importance of continuous rhythmic work. The Chetvertyy Gosudarstvennyy Ordena Lenina Kuybyshevskiy podshipnikovyy zavod (4th State Order of Lenin Kuybyshev Bearing Plant) nd the plant "Avtopribor" in Leningrad are mentioned as plants where single, "advanced", sections and shops do such rhythmic work. There are 3 tables.

Card 1/2



SOV-3-58-10-15/23

AUTHOR:

Boltyanskiy, A.I., Candidate of Economic Sciences, Docent

TITLE:

To Cultivate an Economic Way of Thinking (Vospityvat' eko-

nomicheskoye myshleniye)

PERIODICAL:

Vestnik vysshey shkoly, 1958, Nr 10, pp 74 - 77 (USSR)

ABSTRACT:

An increase in the economic training of prospective engineers can only be attained with the active cooperation of all the chairs of a vtuz. The problems which the various chairs have to face in this connection must be differentiated. For this purpose the Kuybyshev Aeronautical Institute has divided engineering subjects into 3 categories: general theoretical, applied, and specialized. The author states which subjects pertain to the different categories and that the possibilities of furthering the students' economic thinking mount as they transfer from the first to the third group. He describes how the connection between the subject (mathematics, drawing,

Card 1/2

engineering) and economics can be established by the instruc-

To Cultivate an Economic Way of Thinkin

SOV-3-58-10-15/23

tor during the lesson. Other methodical means to cultivate economic thinking are also given: the preparation of special questions on the economics and organization of production during laboratory and other exercises. The article contains 1 table.

ASSOCIATION: Kuybyshevskiy aviatsionnyy institut (Kuybyshev Aeronautical Institute)

SOV/122-59-4-23/28

Boltyanskiy, A.I., Candidate of Economic Sciences, AUTHOR:

Dogent

TITLE: On the Planned and Actual Effectiveness of Technical

Organisation Measures (O raschetnoy i deystvitel'noy

effektivnosti organizatsionno-tekhnicheskikh meropriyatiy)

PERIODICAL: Vestnik Mashinostroyeniya, 1959, Nr 4, pp 78-80 (USSR)

ABSTRACT: Organisational and technical measures are judged by the predicted annual savings and the period during which they pay for themselves. The difference between measures such as design improvements or new production methods which have an integrated effect composed of savings throughout the chain of manufacture and those which have a localised effect, is emphasised. The computation of the actual economies arising from improvements is discussed and illustrated with examples. Again, the effect of improvements in one stage on the total cost must be considered. Some localised improvements yield no overall savings, mostly because of poor coordination with the complete production process. Improvements at

different stages should be complementary. In a factory

Card 1/2 of electrical automotive equipment, a sand blasting

SOV/122-59-4-23/28

On the Planned and Actual Effectiveness of Technical Organisation Measures

installation was replaced with a shot peening plant. The predicted productivity was higher but, owing to the absence of spare parts and an excessive hourly output without accompanying organisational measures to utilise the released time of the operatives, no actual economies were achieved. An automatic machine for assembling roller chains did not yield an overall saving in the absence of measures to speed up preceding operations. Other examples are given showing individual improvements yielding only a fraction of the predicted saving through poor coordination. Reduced machining times led to underloading of machines. The conception of an "implementation factor" for organisational and technical production improvements is introduced.

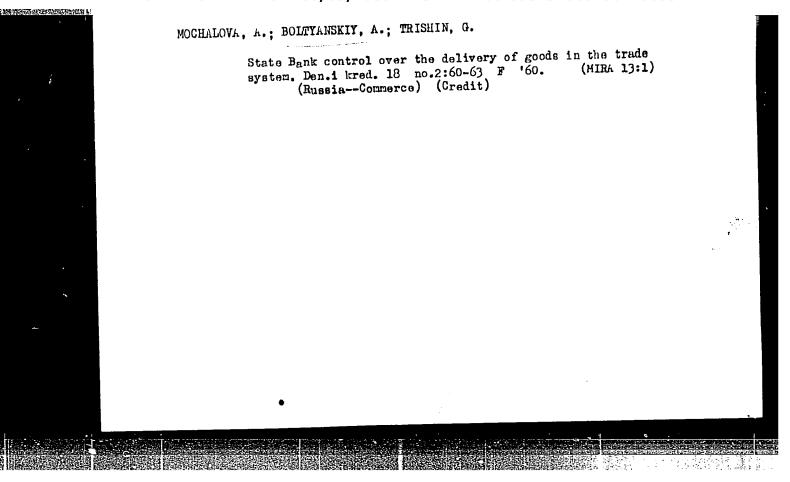
Card 2/2

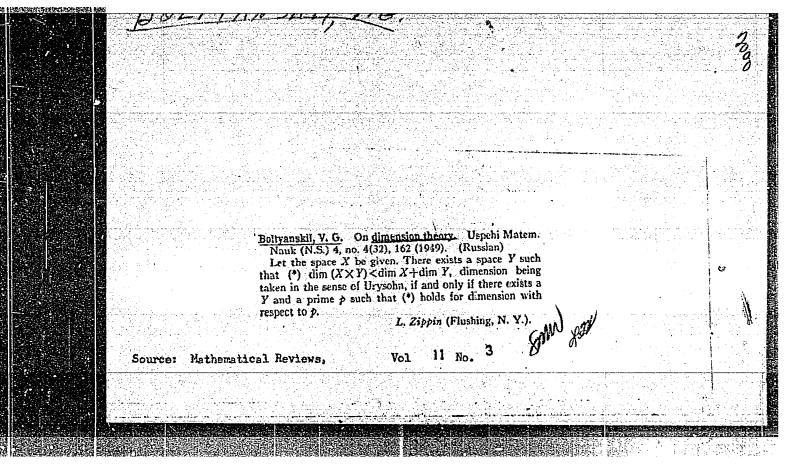
There is 1 table.

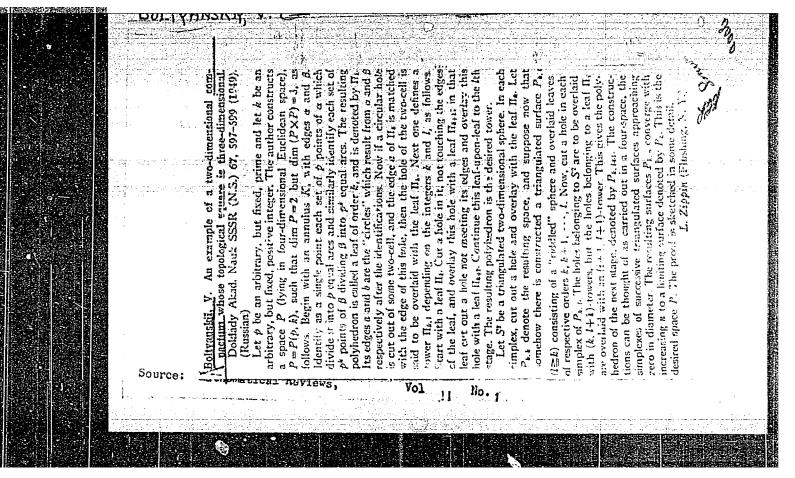
BOLTYANSKIY, A.I. (Assist.Prof.Cand.Econ.Sc.)

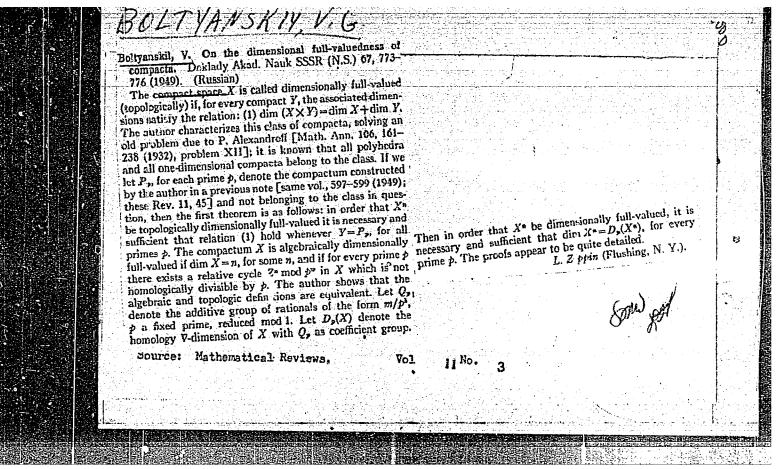
"On certain Processes of Determining Effectiveness of Industrial Improvement."

report presented at the 13th Scientific Technical Conference of the Kuybyshev Aviation Institute, March 1959.









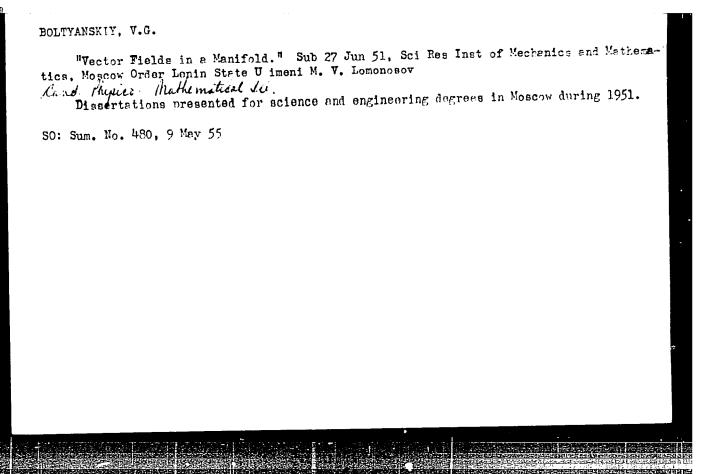
	BOLTYANSKIY V. G.
	Boltyanskii, V. On a property of two-dimensional compacta. Doklady Akad. Nauk SSSR (N.S.) 75, 605-603 (1950). (Russian) For any finite closed covering $\Sigma = (F_1, \dots, F_r)$ of a compactum Φ denote by n_r the number of indices $j \neq i$ for which $F_i \cap F_j \neq 0$. The density of the covering Σ is $\max \{n_1, \dots, n_r\}$. The density of the space Φ is the minimum of those integers n such that for every i there exist finite closed i coverings of i with density i . The author proves that the density of any 2-dimensional compactum is i (and hence that the density of a square is i) and asserts that it is known that the density of a 1-dimensional compactum is 2 or 3.
υ 	Source: Mathematical Reviews, Vol. 13 No.2

The state of the s	BOLTYANSKIY, V.		of complexes $K_{k,l}$; relative cycles of complexes $K_{k,l}$, $\mathbf{x}K_{l,l}$; 2-dimensionality of compacta $P_{m,l}$; dimensionality of compacta $P_{m,l}$; dimensionality of compacta $P_{m,l}$; additivity of dimensions with respect to prime modulus.	1188; SR/Mathematics - Dimension Theory, May/Jun Topology (Contd)	Considers the construction of compacts F, P and their 'inglutination'; dimensions of phi-compactum; Pontryagin's compactum; topological product (production) of structured compacts; relative cycles of complexes K ₁ ; relative cycles of complexes K ₁ = 2-dimensionality of compacts F _m ; dimensionality of the product F _m xF _n ; relative cycles	"Concerning a Theorem on the Addition of Dimen-sions," V. Boltyanskiy "Uspekh Matemat Nauk" Vol VI, No 3 (43), pp 99-128	USSR/Mathematics - Dimension Theory, May/Jun 51
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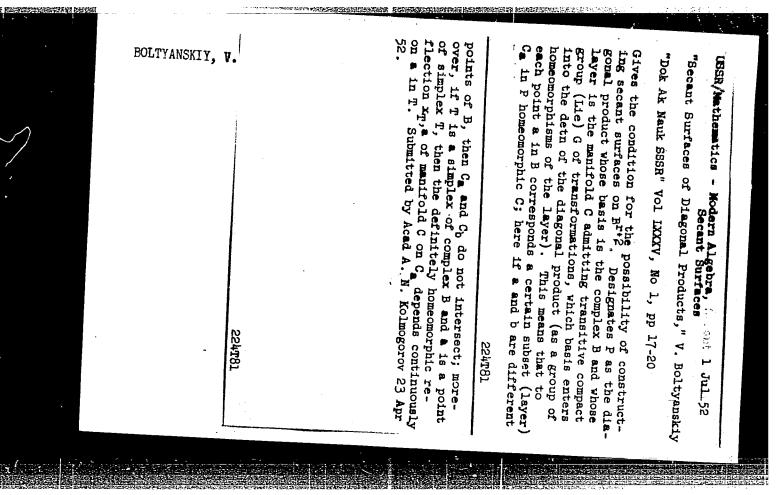
"Construction of a Two-Dimensional Compactum Possessing a Three-Dimensional Topological Square," Usp. Mat. Nauk Vol. 6 No. 4 (44), pp 193-220, 1951.

U-1635, 16 Jan 52

BOLTYANSKTY, V. G.



Submitted 16 May 51. The theorem that geometric dimensions coincide with Uryson dimensions is easily deduced from the fun-Calls dimensions thus obtained by the name geometric coeffs, nor orientations in the cited definition. which to a certain extent is similar to the homologsions," V. G. Boltyanskiy, Moscow author's demonstration here is completely geometrical sults was conducted by algebraic means whereas the dimensions. from the latter in that there are neither groups, ical definition of dimensions, differing however Gives a new definition of the Uryson dimensions, "Matemat Shor" Vol XXIX (71), No 3, pp 603-614 "New Geometric Characteristics of Uryson's Dimen-USSR/Mathematics - Dimensions USSR/Mathematics - Dimensions damental results of the homological theory of BOLTYANSKIY, V. G. However, the demonstration of these re-(Contd) Nov/Dec 51 Mov/Dec 1981 198142 ኳ



CIA-RDP86-00513R000206210003-7 "APPROVED FOR RELEASE: 06/09/2000

USSR/Mathematics - Topology

Card 1/1 Pub. 22 - 1/56

Authors

Boltyanskiy, Vladimir Gricoryevicti

Title

* The problem of taking off a secant surface from a subproduct

Periodical : Dok. AN SSSR 99/5, 669-672, Dec 11, 1954

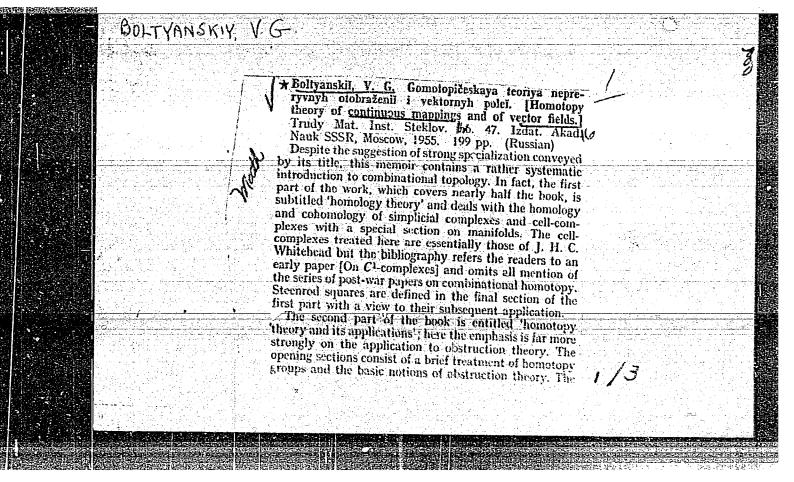
Abstract

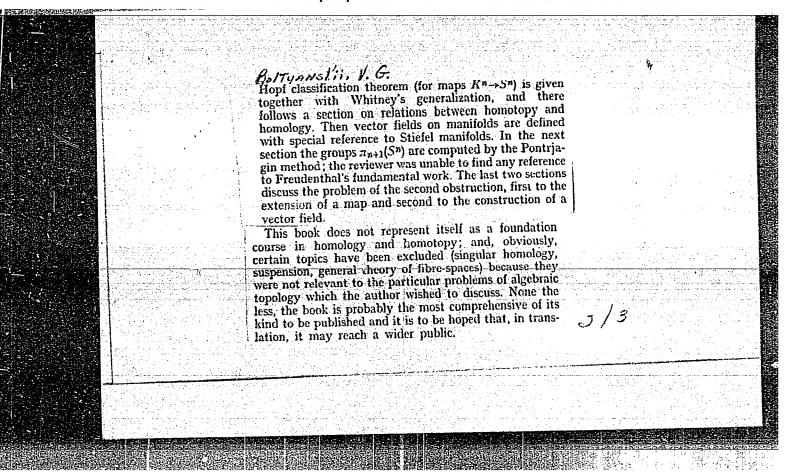
A solution of a problem is given which deals with finding the conditions under which a secant surface $G: B\to P$ of the slant product P can be taken off from a subproduct Q, otherwise, under which conditions the secant surface G: C can be transformed into such a secant surface G: C of the product P: C that G: C (B) C: P/Q: C The symbols B: P: Q: C and P: C: C are defined. Two references 1-USSR (1947 and 1950).

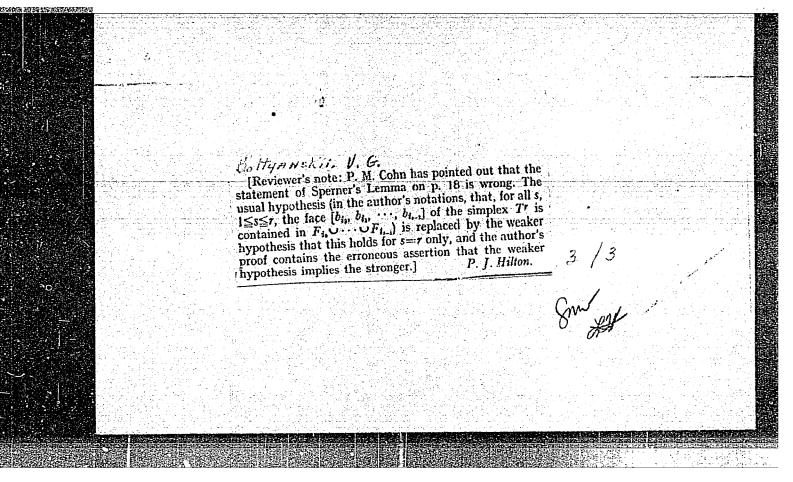
Institution: Mathematical Institute im. A. V. Steklov of the Acad. of Scs. of the USSR

Presented by: Academician P. S. Alexandroff, September 28, 1954

	130L7	YANSKIN	V_{c} , G_{c}		m,
8			V P T Hollyanskii V C.1 Uro Tokob		
0			*Borrmenuli, B. F. [Boltyanskii, V. G.] Tro Toros *Borrmenuli, B. F. [Boltyanskii, V. G.] Tro Toros quedepengapobanko? [What is differentiation?] Go- sudarstv. Izdat. Tehn. Teor. Lit., Moscow, 1955. 63 pp. 90 kopeks. Attempt to explain in a form accessible to students of higher grades of secondary schools certain concepts of higher mathematics such as derivative, differential equa- higher mathematics such as derivative, differential equa-	2	
			higher mathematics such as derivative, different tion, number e, natural logarithm; it is brought out that such concepts are reflections of real processes that take place in nature. Intuitive aspects are stressed sometimes at the expense of rigor.	1/1	
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L.			에는 그렇지 않아 가는 것이 되었다. 장마 사용 사용 기업을 보고 있는 것이 되었다. 그 사용 기업을 보고 있다.		•
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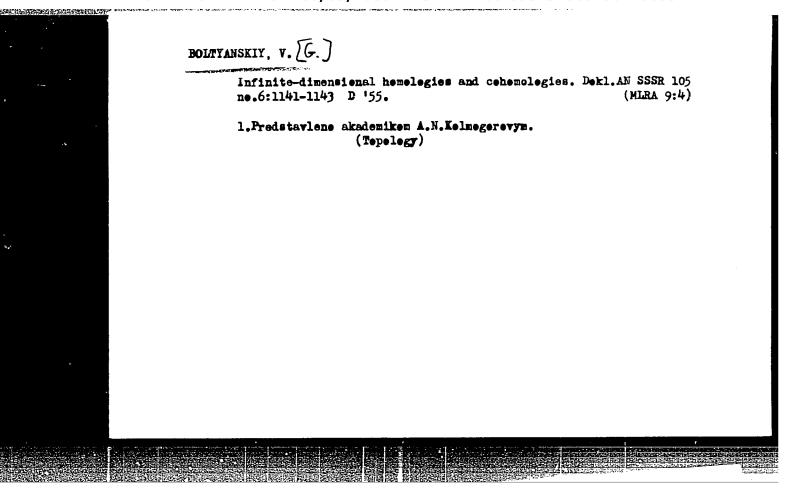


BOLTYANSKIN VLADIMIR GRIGORY EVICH

POLITYAMSKIY, Vladimir Grigor'yevich

BOLTYANSKIY. Vladimir Grigor'yevich, Academic Degree of Doctor of Physico-Mathematical Sciences, based on his defense, 26 May 1955, in the Council of the Mathematics Inst imeni Steklov of the Acad Sci ussr, of his dissertation entitled: "Research on the homotopic theory of intersecting surfaced of oblique works". For the Academic Title of Doctor of Sciences.

SO: Byulleten' Ministerstva, Vysshego Obrazovaniya SSSR, List No 19, 24 Sept. 1955, Decision of Higher Certification Commission Concerning Academic Degrees and Titles.



BOLTYANSKIY, V.G.

USSR/MATHEMATICS/Geometry

CARD 1/1

PG - 592

SUBJECT

AUTHOR

Equally large and decomposition-equal figures. PERIODICAL Moscow: State prolination for technical-theoretical literature

64p. (1956) (Polular lectures on mathematics No. 22).

reviewed 2/1957

The present book gives an introduction to the theory of the contents, where especially the modern results of Hadwiger's school are considered. It first it is shown that for plane polygons the equality of decomposition is equivalent to their equality of contents. Then the theorem of Hadwiger and Glur is shown that the equal polygons can be decomposed such that the corresponding parts are congruent only by means of shiftings and point reflections. Furthermoer it is proved that the group of shiftings and point reflections is also the smallest with respect to which all equal polygons can be decomposed into equivalent parts. In the second part the well-known theorem of Dehn is proved that in the R, there exist volume-equal but not decomposition-equal or completion-equal polyhedra, e.g. cubes and tetrahedra. The proof for this is given in modern form by aid of a lemma of Hadwiger on additive functions of the angles of edges. After a short discussion of the possibilities to define contents by limit values, the theorem of Siedler on the equivalence of decomposition- and completion-equality of polyhedra is proved.

ABRAMOV, A.A., redaktor; BOLTYANSKIY, V.G., redaktor; VASIL'YEV, A.M., redaktor; MEDVEDEV, B.V., redaktor; MISHKIS, A.D., redaktor; NIKOL'SKIY, S.M., otvetstvennyy redaktor; POSTNIKOV, A.G., redaktor; PROKHOROV, Yu.V., redaktor; HYBNIKOV, K.A., redaktor; UL'YANOV, P.L., redaktor; USPENSKIY, V.A., redaktor; CHETAYEV, N.G., redaktor; SHILOV, G.Ye., redaktor; SHIRSHOV, A.I., redaktor; SIMKINA, Ye.N., tekhnicheskikh redaktor

[Proceedings of the third All-Union mathematical congress] Trudy tret'ego vsesciusnogo matematicheskogo s"esda. Moskva, Izd-vo Akademii nauk SSSR. Vol.1. [Reports of the sections] Sektsionnye doklady. 1956. 236 p. (MLRA 9:7)

1. Vsesoyuznyy matematicheskiy s*yezd.3rd Moscow, 1956.
(Mathematics)

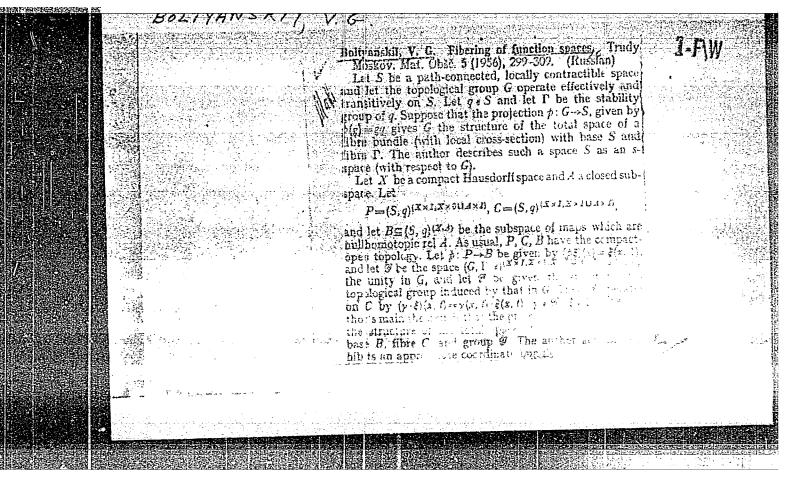
ABRAMOV, A.A., redaktor; BOITYANSFIY, W.A., redaktor; VASIL'YEV, A.M., redaktor; MEDVEDEV, B.V., redaktor; MYSHKIS, A.D., redaktor; NIKOL'SKIY, S.M., otvetstvennyy redaktor; POSTNIKOV, A.J., redaktor; PROKHOROV, Yu.V., redaktor; RYBNIKOV, K.A., redaktor; UL'YANOV, P.L., redaktor; USPENSKIY, V.A., redaktor; CHETAYEV, N.G., redaktor; SHILOV, G.Ye., redaktor; SHIRSHOV, A.I., redaktor; SIMKINA, Ye.H., tekhnicheskiy redaktor

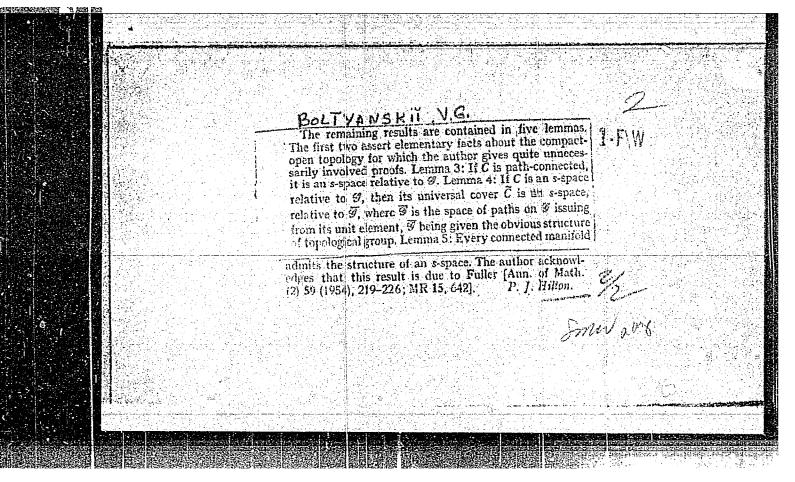
[Proceedings of the all-Union Mathematical Congress] Trudy tret'ego vsesoiuznogo Matematicheskogo s"ezda; Moskva iiun'-iiul' 1956.

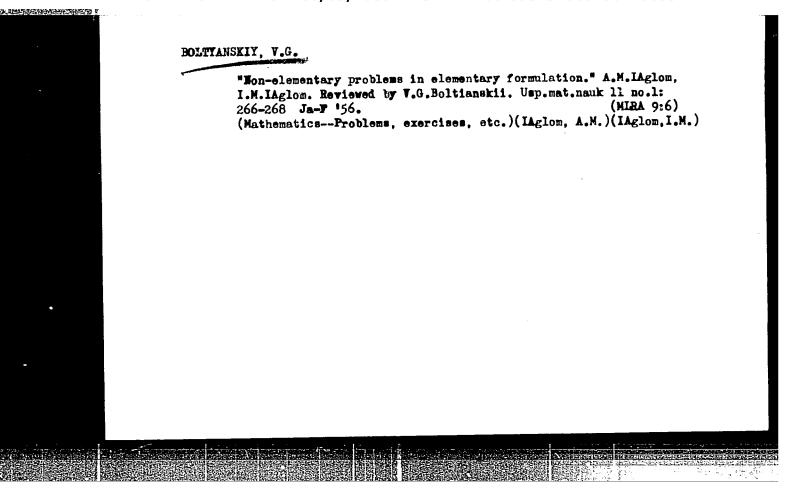
Moskva, Izd-vo Akademii nauk SSSR. Vol.2. [Brief summaries of reports] Kratkoe soderzhanie obzornykh i sektsionnykh dokladov.

1956. 166 p. (MLRA 9:9)

 Vsesoyuznyy matematicheskiy s*yezd. 3, Moscow, 1956. (Mathematics)







PG - 35

GDLTYANSHY, V SUBJECT USSR/MATHEMATICS/Topology CARD 1/2

AUTHOR BOLTJANSKIJ V.G.
TITLE The second impediments for intersection surfaces.

TITLE The second impediments for interest 1956)
RERIODICAL Izvestija Akad. Nauk, Ser. mat. 20, 99-136 (1956)

reviewed 5/1956

Let P be a fibre bundle with a complex B as basis, with a fibre C being aspherical in the dimensions $\langle r (r \geqslant 2) \rangle$ and with a connecting structure group G operating effectively and transitively on C which possesses a local intersection surface (e.g. a Lie group). Further let the isotropy group $\Gamma \subseteq G$ be continuous-connecting and the characteristic class of cohomologies $Y^{r+1} \in \nabla^{r+1}(B, \pi^r(C))$ of the bundle B be equal zero. Then there exists an intersection surface T of P over B^{r+1} . The author determines the second impediment $Z^{r+2}(T) \in \nabla^{r+2}(B, \pi^{r+1}(C))$ against the continuation of T on T we have T as an arbitrary intersection surface over T and T and T are T as the impediment against the continuation on T for a mapping T is the impediment against the constant mapping of T has a difference cocycle T in T and T are T explicit expressions are difference cocycle T in T and T are T explicit expressions are

SUBJECT AUTHOR TITLE PERIODICAL USSR/MATHEMATICS/Differential equations CARD 1/3 PG - 707
BOLTJANSKIJ V.G., GANKRELIDZE R.V., PONTRJAEIN L.S.
On the theory of optimal processes.
Doklady Akad.Nauk 110, 7-10 (1956)
reviewed 4/1957

The problem of the quality of control being actual in the theory of automatic control is represented in general form and is considered.

Let be given the system $\dot{x}^1 = f^1(x^1, \dots, x^n; x^1, \dots, u^r) = f^1(x, u), \quad (i=1,\dots,n),$ where $x = (x^1,\dots,x^n)$ is the image point in the n-demensional phase space and $u = (u^1,\dots,u^r)$ is the "controlling vector". If u(t) is piecewise smooth and continuous and if it belongs to a fixed closed region Ω of the variables and continuous and if it belongs to a fixed closed region Ω of the variables u^1,\dots,u^r , where Ω has a piecewise smooth (n-1)-dimensional boundary, then u(t) is called permissible.

Formulation of the problem: In the phase space x^1,\dots,x^n two points x_0 and x_0 are given. A permissible control vector x_0 is to be chosen in such a way that the point of the phase space comes from the position x_0 to the position x_0 is minimal time. Assuming the existence of a solution and if u(t) is the optimal vector and x_0 the corresponding optimal path, then to the somewhat deviating vector $u(t) + \delta u(t)$ there corresponds the path x_0 . In linear approximation we have

and ψ let $H(x, \psi, u) = \psi_{\alpha} f^{\alpha}(x, u)$ have a maximum $m(x, \psi)$ in u if u changes in Ω .

*Doklady Akad. Nauk 110, 7-10 (1956)

HEALER HELDER

CARD 3/3

PG - 707

'If the 2n-dimensional vector (x, y) is a solution of the system

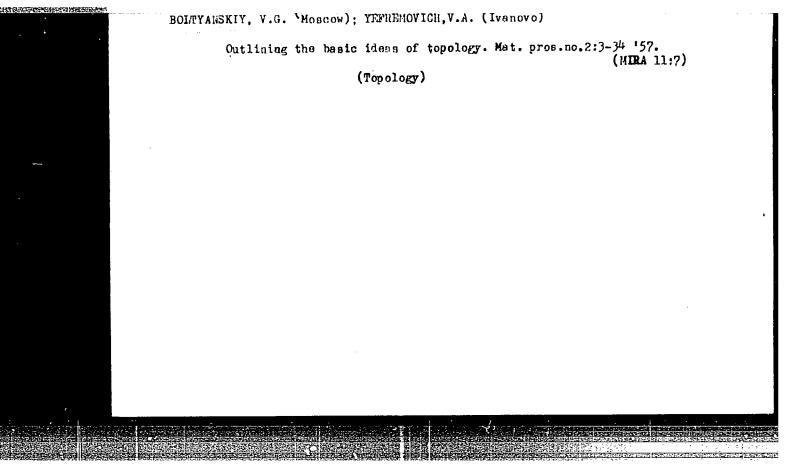
(2)
$$\dot{x}^{i} = f^{i}(x,u) = \frac{\partial H}{\partial \psi_{i}}$$

$$\dot{\psi}_{i} = -\frac{\partial f^{\alpha}}{\partial x^{i}} \psi_{\alpha} = -\frac{\partial H}{\partial x^{i}}$$

$$i=1,...,n,$$

where the piecewise continuous vector $\mathbf{u}(t)$ always satisfies the condition $\mathbf{H}(\mathbf{x}(t), \mathbf{\psi}(t), \mathbf{u}(t)) = \mathbf{M}(\mathbf{x}(t), \mathbf{\psi}(t)) > 0$, then $\mathbf{u}(t)$ is the optimal control and $\mathbf{x}(t)$ is the corresponding locally optimal path. Starting from a fixed initial condition $\mathbf{x}(t_0) = \mathbf{x}_0$ and changing the condition $\mathbf{\psi}(t_0) = \mathbf{y}_0$, then (2) with these conditions and the condition $\mathbf{H}(\mathbf{x}(t), \mathbf{\psi}(t), \mathbf{u}(t)) = \mathbf{H}(\mathbf{x}(t), \mathbf{\psi}(t)) > 0$ determines the set of all locally optimal paths through the point $\mathbf{x}_0 = \mathbf{x}(t_0)$ and the corresponding optimal control mechanisms $\mathbf{u}(t)$.

INSTITUTION: Math.Inst.Acad.Sci.



BOLHYALSKIY, V.G., red.; DYHKIMA, Ye.B., red.; POSTNIKOV, M.M., red.;

SOLD/ENTSEV, Ye.D., red.; IOVLEVA, N.A., tekhn.red.

[Fiber spaces and their applications; collection of translations]

Kassloennye prostranstva i ikh prilozhenile; sbornik perevodev.

Moskva, Izd-vo inestr.lit-ry, 1958, 460 p. (MIMA 12:1)

(Topelegy)

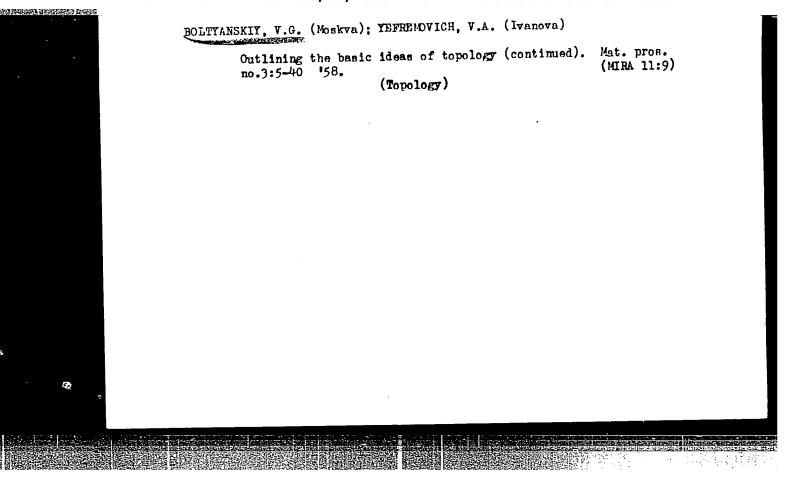
NIKO. SKIY, S.M., otv.red.; ABRAMOV, A.A., red.; BOLTYANSKIY, W.G., red.; VASIL'YEV, A.M., red.; MEDVEDEV, B.V., red.; MYSHKIS, A.D., red.; POSTNIKOV, A.G., red.; PROKHOROV, Yu.V., red.; RYBNIKOV, K.A., red.; UL'YANOV, P.L., red.; USPENSKIY, V.A., red.; CHETAYEV, N.G., red.; SHILOV, G.Ye., red.; SHIRSHOV, A.I., red.; GUSEVA, I.N., tekhn.red.

[Proceedings of the Third All-Union Mathematical Congress] Trudy
tret'ego Vaesoiusnege matematicheskogo s'ezda. Vel.3 [Synoptic
papers] Obzornye doklady. Moskva, Izd-vo Akad.nauk SSSR. 1958. 596 p.
(MIRA 12:2)

1. Vsesoyuznyy matematicheskiy seyezd. 3d. Moscow, 1955.

(Mathematics--Congresses)

APPROVED FOR RELEASE: 06/09/2000 CIA-RDP86-00513R000206210003-7"



AUTHOR:

Boltvanskiy, V.G. (Moscow)

SOV/39-46-1-5/6

TITLE:

Homotopic Classification of the Secant Surfaces (Gomotopiches-

kaya klassifikatsiya sekushchikh poverkhnostey)

PERIODICAL:

Matematicheskiy sbornik, 1958, Vol 46, Nr 1. pp 91-124 (USSR)

ABSTRACT:

The paper consists of six paragraphs. The first five contain, partially with and partially without proof, well-known results of Steenrod, Pontryagin and Postnikov and form the basis for the last paragraph, in which the general classification theorem for secant surfaces of an oblique product is proved (necessary and sufficient conditions for the homotopy). From this general criterion the classification theorems of Steenrod, Pontryagin and Postnikov can be concluded. The proofs for some results of Postnikov [Ref 5,6] which have not been published till now,

seem to be of interest.

There are 15 references, 10 of which are Soviet, 4 American,

and 1 Swiss.

SUBMITTED:

March 26, 1957

Card 1/1

ni producentalicani BOLTYANSKIE 20-118-1-2/58 BOLTYANSKIY, V.G. Homotopic Classification of Vector Fields (Gomotopicheskaya AUTHOR: klassifikatsiya vektornykh poley) Doklady Akademii Nauk/1958, Vol 118, Nr 1 pp 13-16 (USSR) TTLE: The author gives a homotopic classification of the vector PERIODICAL: fields on n-dimensional manifolds. In the case $n \leqslant 5$ this ABSTRACT: is a trivial consequence of well-known facts. For n > 4 the classification follows from the author's results [Ref.4] on the homotopic classification of the secant surfaces and consists in the fact that to each element of an integer cohomology group Hn-1(Mn) for n>4 there correspond exactly two classes of vector fields. Theorem: Let Kn be a simplicial decomposition of the n-dimensional manifold M^n . Let two vector fields on K^n be denoted (n-1)-homotopic, if, considered only on the (n-1)dimensional K^{n-1} , they are homotopic. Then the elements of the group $H^{n-1}(M^n)$ biunivoquely correspond to the (n-1)homotopy classes of the vector fields on M^n . For $n \gg 4$ each (n-1)-homotopic class is decomposed into exactly two homotopy classes, which gives for n > 4 a complete classification

Card 1/2

20-118-1-2/58

Homotopic classification of Vector Fields of the vector fields on $M^{\mathbf{n}}$. 3 Soviet and 5 foreign re-

ferences are quoted.

ASSOCIATION: Matematicheskiy institut imeni V.A. Steklova, Akademii nauk

SSSR (Mathematical Institute imeni V.A. Steklov, Academy of

Sciences, USSR)

June 25, 1957, by P.S. Aleksandrov, Academician PRESENTED:

June 24, 1957 SUBMITTED:

Library of Congress AVAILABLE:

Card 2/2

AUTHOR:

Boltyanskiy, V.G.

The Maximum Principle in the Theory of Optimum Processes

(Printsip maksimuma v teorii optimal'nykh protsessov)

PERIODICAL: Doklady Akademii nauk SSSR,1958, Vol 119, Nr 6, pp 1070-1073 (USSR)

ABSTRACT: Let the motion of the point $x = (x^1, ..., x^n)$ in the n-dimensional phase space X be described by

 $\dot{x} = f^{\dot{1}}(x^{\dot{1}},...,x^{\dot{n}},u) = f^{\dot{1}}(x,u)$ i=1,...,n.

The "steering parameter" u=u(t) is to be chosen in an arbitrary topological space U so that the point comes from the position $x_0 \in X$ into the position $x_1 \in X$ in a minimum of time. Then the

process $\mathbf{x}=\mathbf{x}(t)$ is called optimum. In a common paper of the author, Pontryagin and Gamkrelidze In a common paper of the author, Pontryagin and Gamkrelidze [Ref 1] the author conjectured a certain general maximum principle. In the present paper the author proves the correctness of this conjecture, namely it holds the theorem: In order that the process $\mathbf{x}=\mathbf{x}(t)$, $t_0 \leqslant t \leqslant t_1$, runs optimally for the steering $\mathbf{u}(t)$, it is necessary that there exists a vector $\mathbf{\Psi}(t)$

card 1/2 so that $H(x(t), \Psi(t), u(t)) = \max_{u \in U} H(x(t), \Psi(t), u) \geqslant 0$

The Maximum Principle in the Theory of Optimum Processes 20-117-0-7777 where H is a certain well-defined function. Furthermore it is proved that H is constant along x(t), $\psi(t)$ and u(t) $(t_0 \le t \le t_1)$.

 $\mathbf{u}(\mathsf{t})$ is assumed to be piecewise continuous. There is 1 Soviet reference.

ASSOCIATION: Matematicheskiy institut imeni V.A. Steklova Akademii nauk SSSR (Mathematical Institute imeni V.A. Steklov of the Academy of Sciences of the USSR)

PRESENTED: December 19, 1957, by P.S.Aleksandrov, Academician

SUBMITTED: December 18, 1957

Card 2/2

PHASE I BOOK EXPLOITATION:

متحقر المماح

Matematika v SSSR za sorok let, 1917-1957, tom 2: Biobibliografiya (Mathematics in the USSR for Forty Years, Vol 2: Biobibliography) Moscow, Fizmatgiz, 1959. 819 p. Errata slip inserted. 6,000 copies printed.

Eds.: A. G. Kurosh (Chief Ed.), V. I. Bityutskov, V. G. Boltyanskiy, Ye. B. Dynkin, G. Ye. Shilova, and A. P. Yushkevich; Tech. Ed.: S. N. Akhlamov.

PURPOSE: This book is intended for mathematicians and science historians.

COVERAGE: This is the second of a two-volume work. It contains contributions of Soviet mathematicians for the period 1917-1957 and was compiled by Yu. A. Gor'kov. Ke. Ye. Chernin wrote the part pertaining to the approximation method and "machine" mathematics. This includes bibliographic material from "Mathematics in the USSR for 15 Years" and "Mathematics in the USSR for 30 Years". A significant part of the bibliographic material has been checked against lists of works sent to the editor by various scientists. The authors are presented in alphabetical order, while the works of each author are arranged chronologically. At the end of the book is a list of the basic mathematical journals of the world. Some 22,000 is a list of works of more than 3,600 authors are given (in "Mathematics in titles of works of more than 3,600 authors are given (in "Mathematics in the USSR for 30 Years", there are about 7,000 works and 1,300 authors).

Card 1/2

The book emphasizes those works which are important either for the mathematical methods presented in them or for their statement of mathematical problems. As a rule, no publications on mathematical methodology and pedagogic literature are included; the latter is represented only by existing university textbooks. In addition to the bibliographic material, the book contains a large amount of biographic data on Soviet mathematicians. This biographic material was assembled by R. S. Bityutskova, mainly on the basis of information sent to the editor. The book also gives information on reviews of the works of Soviet scientists in journals and articles from "Mathematics in the USSR for 30 Years", "Mathematics in the USSR for 15 Years", and from the first volume of the present work, "Mathematics in the USSR for 40 Years", referred to in the book by the following symbols respectively: M-XV, M-XXX, and M-XL.

TABLE OF CONTENTS: None given.

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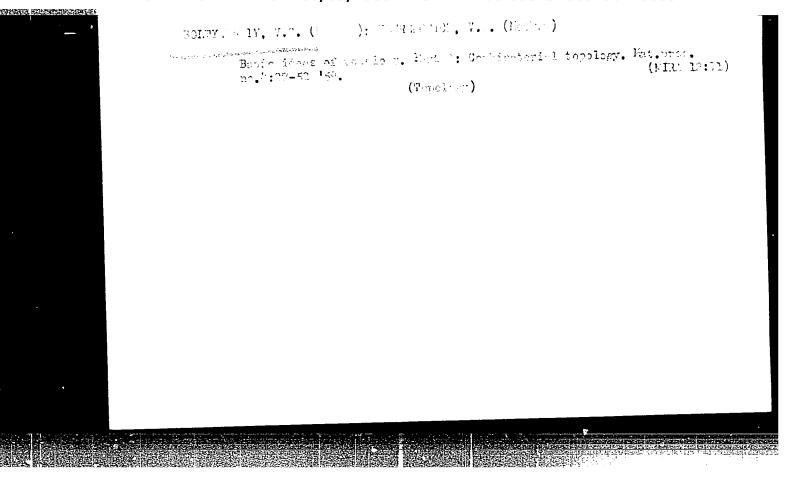
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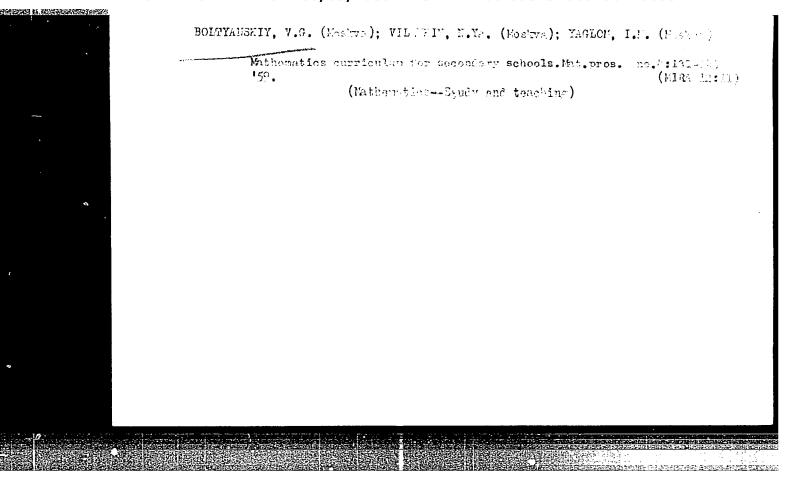
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BOOK EXPLOIMATION SOW/2508 *** ** ** ** ** ** ** ** ** ** ** ** **	MA: I.W. Bronnshay, Editorial Board of Series: 1.W. Bronshteyth, A.F. Markusheyth, I.W. Taglos, Tech. Ed.: 5.W. Akhlanov. PURPOSE: This book is intended for persons without an extensive C. seaporty mathematics. The book may be useful to high school atthematics. The book may be useful to high school.	COVERAGE: The book consists of articles, reviews, and scientific and subtodological reports, some of which are transitions from other lunguages. The state of sactrum mathematical is covered, its climing applications, history, tendoning of anthematica in schools, and anthematical developments in the USRS and shroad. One section deals with selemptic and podagogical life in the USRS and inches contains reviews of certain mathematical publications. Some mathematical background is necessary to understand the book certain articles require a knowledge of higher mathematical sections.	REVIEWS, ANTICLES, TRANSLATIONS	Numererals, L.A. On the Computation of Values of Punctions of One Variable (Conclusion) Boltyanskiy, V.Q., and V.A. Yefremovich. Outline of the Punda-	inuation) by of Games (Translation from ited by V.B. Grlov)	Mathematics in Poland (translated from	Balada, F. (Gzonoslovakta) Prief Historical Survey of the Crech Mathematica and Physics Jociety (Abridged Translation from Crech by Yu.M. Gayduk)	Stone, M., (USA) Mathematics and the Puture of Science (Translation from English by L.A. Markusherich under the editorship of A.I. 111 Markusherich)	On the Problem of Reform of the Teaching of Mathematics in Secondary Schools	kin, I.M. Yaglom, On the Contenta ion Course	Cortain Problems of Teaching Mathamatics in Secondary	Replies: 1. Do nt Exci the ines of the Axionatic Method From the School 1. (Bronstein, I.M., and A.M. Lopshits) Card 3/8	
16(1) FRASE I Matematioheskoye prosvembohadiy prilosheskya i Matomyayay vyj Mathematios, Ita Tambings i Mathematios, Ita Tambings i	Ed. I. M. Brombteyn J. Editori A. J. Markubevich, I.W. Tain PURPOSE: This book is intended machesation ducation who sabsestion the section. The	COVERAGE: The book consists of and such cathodological response, other languages. The state standards applications, his schools, and matches total one section deals with sever eations. Some matches the book certain articles amatics.	TABLE OF CONTENTS: I. REVLEMS,	Lyusternik, L.A. On the Comput One Variable (Conclusion) Holtranskiy, V.Q., and V.A. Yei	menti Idess of Topology (Continuation) Bohnemblust, M.P., (USA), Theory of Games (Translation from English by Pu.V. Geronisms, edited by V.B. Orlov)	Barpinskir, V.; (Poland) Mathe French by M.G. Sheatopal) Card 2/8	Balada, F. (Greencelovakia) E Mathematica and Physics Jociety by Yu.W. Gayduk)	Stone, M., (USA) Mathematics of from English by L.A. Markushevich)	On the Froi	Prom the Editor Boltyanskir, W. M. Ya. Vilenkin, I.M. Yaglom, of a Secondary School Mathematics Course	Levin, V.I. Cortain Problems School	Replies: L. Donnestein, I.N., and A. Card 3/8	
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		copies	side,	19. 10.	COVINAME: This book is wolume I of a major 2-volume work on the history of Sovier mathematica. Volume I surveys the chief contributions made by Sovier mathematical during the period 1947. Johns II will contain a bibliography of major works since ticians. This work follows the tradition set by two earlier the user in This work follows the tradition set by two earlier the USAR for 15, Years and for the substitution of the follows the tradition of the factor of the major is the USAR for 15 fears and the USAR for 16 fears. The book is a tridetair let factor be major divisions of the feat, i.e., algebra, topolay trobusts of probabilities, functional analysis, etc., and contributions and outstanding problems in each discussed. A list-ences to their contributions in the fiald.	201	5883 5883	2250 2250 2250	229	230	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	263	263	276 276 286	285 291
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Optimal processes with parameters. Dokl. AN Uz. SSR no.10:9-12
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1. Institut matematiki AN UzSSR. Predstavleno akademikom AN UzSSR
T. A. Sarymsakovym.

(Differential equations)

SOV/38-23-6-5/11 16(1) 16.5400 16.5500 Boltyanskiy, V.G. AUTHOR: Mappings From Compacts Into Euclidean Spaces Izvestiya Akademii nauk SSSR, Seriya matematicheskaya, 1959, TITLE: Vol 23, Nr 6, pp 871 - 892 (USSR) PERIODICAL: The mapping f of the compact X into an Euclidean space is called k-regular (k>1) according to K. Borsuk / Ref 4_7, ABSTRACT: if for arbitrary different k + 1 points x_0, x_1, \dots, x_k of X the points $f(x_0)$, $f(x_1)$,..., $f(x_k)$ do not lie in a (k - 1)-dimensional plane. The author considers the following embedding problem: Determine the smallest natural N so that for dim E>N the set of all k-regular mappings of an arbitrary n-dimensional compact X into the Euclidean space E is everywhere dense in the set of all continuous mappings $X \longrightarrow E$. The main result of the paper is the statement : N = n + n + k. For the proof the author gives at first a generalization of the well-known embedding theorem of Pontryagin-Nöbeling (theorem 3). From this it follows theorem 1 : Let E be an Euclidean space of the dimension > n k + n + k and f an arbitrary mapping of the n-dimensional compact X into E. Then for every $\epsilon > 0$ there exists a k-re-

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Card 1/2

Mappings From Compacts Into Euclidean Spaces

sov/38-23-6-5/11

gular mapping $\psi: X \to E$ which differs from f by less than $\mathcal E$. Theorem 2 is known (Hurewicz / Ref 6 7). Theorem 4 is the infinite-dimensional analogue of theorem 1. From theorem 1 it follows: $N' \le n \ k + n + k$. The proof of the main result is concluded by the proof of the inequality $N' \ge n \ k + n + k$. There are 7 references, 3 of which are Soviet, and 4 German.

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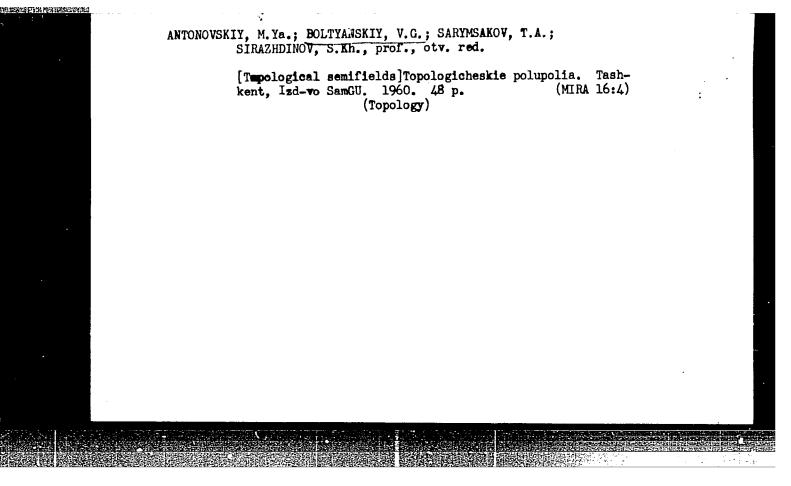
by P.S. Aleksandrov, Academician

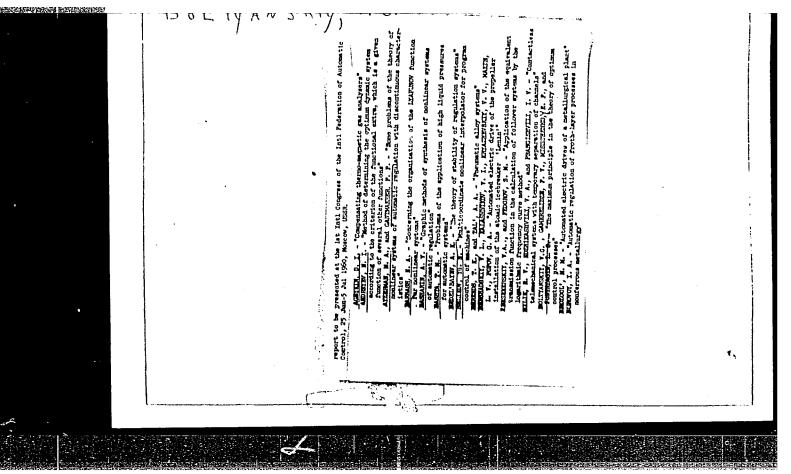
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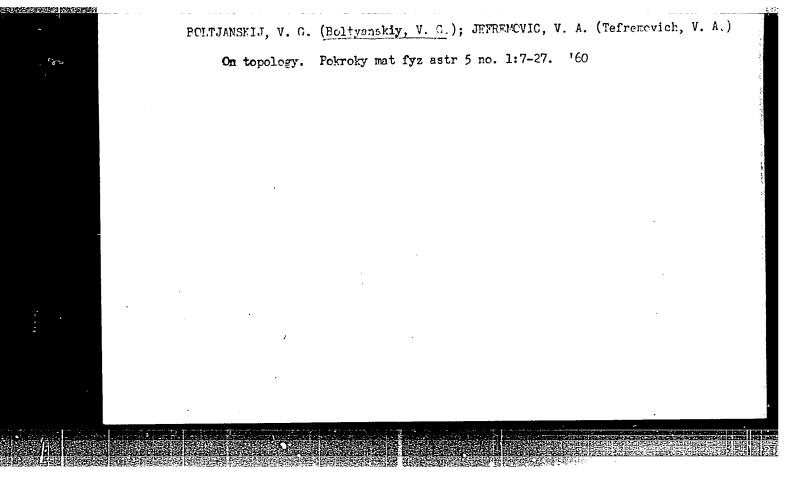
January 3, 1959

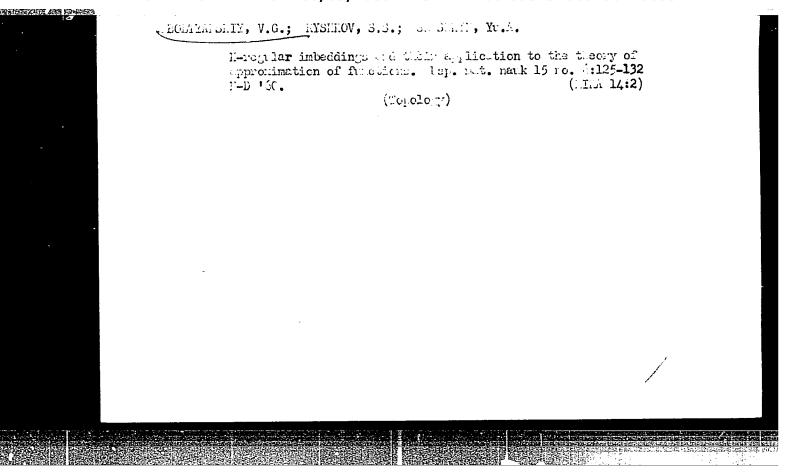
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Card 2/2









16(1)

AUTHORS:

\$/038/60/024/01/001/006 Boltyanskiy, V.G., Gamkrelidze, R.V.

and Pontryagin, L.S.

TITLE:

Theory of Optimal Processes. I Maximum Principle

PERIODICAL: Izvestiya Akademii nauk SSSR. Seriya matematicheskaya, 1960,

Vol 24, Nr 1, pp 3-42 (USSR)

ABSTRACT:

The paper contains a detailed representation of the results

published by the authors in _Ref 1-6, 10_7. At the Mathematical Congress in Edinburgh L.S. Pontryagin has

reported about the most essential results.

There are 10 references, 7 of which are Soviet, 1 German,

and 2 American.

SUBMITTED: May 14, 1959

Card 1/1

36463 \$/020/60/133/004/032/040 XX C111/C333

16.2200

Boltyanskiy, V.G., Postnikov, M.M.

TITLE: On Principal Notions of Algebraic Topology. Axiomatic Definition of Cohomology Groups

PERIODICAL: Doklady Akademii nauk SSSR, 1960, Vol. 133, No. 4, pp. 745 - 747

The objects of a category of are assumed to be topological spaces with marked points, the mappings of \mathcal{O}_0 are assumed to be continuous and to transfer marked points into marked points. Let 0_{χ} be a marked point of the space X. Let IX be the topological product $[0,1] \times X$ in which $[0,1] \times 0_X$ is drawn together into the point $0 = 0_{1X}$. Let the mapping $X \rightarrow IX$ defined by $x \rightarrow (t,x)$ be denoted by q_t . For every $f: X \rightarrow Y$ let If denote the mapping IX-IY defined by $q_t(x) \rightarrow q_t(f(x))$. Card 1/4

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On Principal Notions of Algebraic Topology. Axiomatic Definition of Cohomology Groups

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to C, then also the mappings f,g are to belong to $\mathcal U$. Let C admissible and fixed. Spaces and mappings of $\mathcal U$ then are called admissible e too. The cofibrings (*) with admissible X,Y,Z are called admissible too. Admissible mappings f_0 , f_i : $X \rightarrow Y$ are called homotopic (in $\mathcal U$), if there exists an F: $IX \rightarrow Y$ such that $F \circ q_i = f_i$, i = 0,1.

Let to every integer n a contravariant functor H^n be given which is defined in \mathbb{C} and attains values in the category of the abelian groups and their homomorphisms. Then three functors H^n_I , H^n_{III} are defined on the category of all admissible cofibrings (and of their admissible mappings). H^n_I makes correspond the group $H^n(X)$ to the cofibring (*), $H^{(n)}_{III}$ the group $H^n(Z)$. The functors H^n form the group theory of the cohomologies, if for every n a natural transformation S^n from H^n_I into H^{n+1}_{III} is given and if the following axioms are satisfied:

1^H. The groups $H^{n}(S^{0})$ are trivial for $n \neq 0$. Gard 3/4

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On Principal Notions of Algebraic Topology. Axiomatic Definition of Cohomology Groups

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 2^{H} . For arbitrary admissible mappings $f,g: X \rightarrow Y$ which are mutually homotopic the homomorphisms $H^{n}(f)$, $H^{(n)}(g): H^{n}(Y) \rightarrow H^{n}(X)$ are identical.

 3^{H} . For every admissible cofibring $X \xrightarrow{f} Y \xrightarrow{g} Z$ it holds the rigorous sequence

 $\dots \to H^{n}(z) \xrightarrow{H^{n}(g)} H^{n}(Y) \xrightarrow{H^{n}(f)} H^{n}(X) \xrightarrow{\int^{n} H^{n+1}(z) \to \dots}$

 $H^0(S^0)$ is called group of coefficients of the theory considered. The same axioms (correspondingly changed) describe the homology groups. There are 2 American references.

ASSOCIATION:

Matematicheskiy institut imeni V.A. Steklova Akademii nauk SSSR (Mathematical Institute imeni V.A. Steklov of the Academy of

Sciences USSR)

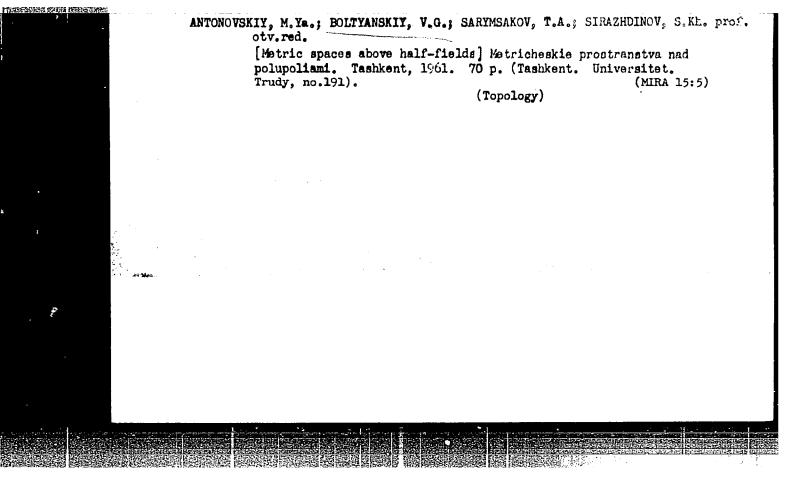
PRESENTED:

May 10, 1950, by I.M. Vinogradov, Academician

SUBMITTED: May 9, 1960

Card 4/4

X



BOLITANSKIY, Vladimir Grigor'yevich; CHERNYSHEVA, L.Yu., red.; LIKHACHEVA, L.V., tekhn. red.

[Envelopes] Ogibaiushchaia. Moskva, Gos. izd-vo fiziko-matem. lit-ry, 1961. 75 p. (Populiarnye lektsii po matematike, no.36) (MIRA 14:10)

(Envelopes (Geometry))

PONTRYAGIN, Lev Semenovich; BOLTYANSKIY, V.G., red.; BAYEVA, A.P., red.; YERMAKOVA, Ye.A., tekim. red.

[Ordinary differential equations] Obyknovennye differentsial'nye uravneniia. Moskva, Gos. izd-vo fiziko-matem. lit-ry, 1961. 311 p.

(Differential equations)

(Differential equations)

BOLTYANSKIN V.G.

PHASE I BOOK EXPLOITATION

SOV/5883

rontryagin, Lev Semenovich, Vladimir Grigor'yevich Boltyanskiy, Revaz Valerianovich Gamkrelidze, and Yevgeniy Frolovich Mishchenko

Matematicheskaya teoriya optimal'nykh protsessov (Mathematical Theory of Optimum Processes) Moscow, Fizmatgiz, 1961. 391 p. 10,000 copies printed.

Ed.; N. Kh. Rozov; Tech. Ed.; K. F. Brudno.

This book is intended for specialists concerned with the mathematical PURPOSE 8 theory of optimum control processes.

COVERAGE: The book contains a systematic presentation of results on the theory of optimum control processes obtained by the authors during the years 1956-1961. Some data obtained from other scientists are also included. The authors' socalled "Principle of Maximum" makes possible the solution of a considerable number of variational problems of nonclassical type associated with the optimization of controlled processes. The principle is presented in detail and is compared with Bellman's principle of dynamic programming. A series of problems on optimum processes is studied on the basis of general methods of the Principle

Card 1/6

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Boltyanskiy, V.G., Gamkrelidze, R.V., Mishchenko, Ye. AUTHORS:

F., and Pontryagin, L.S. (USSK)

Principle of maximum in the theory of optimal TITLE:

processes

IFAC, lst Congress, Moscow 1960. Teoriya diskretnykh, SOURCE:

optimal'nykh i samonastraivayushikhsya sistem.

Trudy, v. 2, 1961, 457 - 470

TEXT: The general optimum problem is formulated, as well as the basic results obtained by the authors. The n-dimensional phasespace Xn is considered, and the controlled object (plant) is described by the vector equation

 $\dot{x} = f(x, u), \dot{r} = (f^1, ..., f^n);$

is the class of allowed controllers is defined as the class of piecewise linear functions u(t), $t_1 \le t \le t_2$. The optimum problem is formulated as follows: The two points ξ_1 , ξ_2 are given in X^n ; it

Card 1/6

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Principle of maximum in the theory ...

is required to choose, among the allowed controllers, a controller u(t), so that the corresponding trajectory x(t) of Eq. (2), defined on the entire interval $t_1 \le t \le t_2$, connects the points x_1, x_2, x_3 ($x(t_1) = x_1, x(t_2) = x_2, x_3$), and the integral

$$\int_{t_1}^{t_2} f_0(x(t), u(t)) dt$$
 (3)

Ŋ

is minimized. Any allowed controller which satisfies the above conditions, is called the optimal controller, and the corresponding trajectory — optimal trajectory. Depending on the choice of the function $f^0(x, u)$ integral (3) may represent the time elapsed, the fuel, energy, etc. spent during the process. The necessary conditions which any optimal controller and its corresponding trajectory satisfies, are expressed by the following basic theorem 1, called the principle of maximum. Preliminarily, the vector \bar{x} of (n+1)-dimensional space \bar{x}^{n+1} is introduced, as well as the covariant vector \bar{y} and the scalar function

Card 2/6

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Principle of maximum in the theory ...

$$H(\overline{\psi}, x, u) = \sum_{\alpha=0}^{n} \psi_{\alpha} f^{\alpha}(x, u)$$
.

Thereupon the Hamiltonian system of equations

$$\hat{\mathbf{x}}^{i} = \frac{\partial \mathbf{H}(\overline{\mathbf{\Psi}}, \mathbf{x}, \mathbf{u})}{\partial \mathbf{\Psi}_{i}}, \quad i = 0, \dots, n$$
 (6)

$$\dot{\psi}_{\mathbf{i}} = \frac{\partial H(\overline{\psi}, \mathbf{x}, \mathbf{u})}{\partial \mathbf{x}^{\mathbf{i}}}, \mathbf{i} = 0, \dots, n$$
 (7)

is set up. The notation

$$M(\overline{\psi}, x) = \sup_{u \in \Omega} H(\overline{\psi}, x, u)$$

is used. Theorem 1 (principle of maximum): Let u(t) be the optimum controller and x(t) — the corresponding optimum trajectory of (2). Then the nonzero, covarient, continuous function $\psi(t)$ can be found

Card 3/6

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Principle of maximum in the theory ... D298/D302

so that the coordinates x^1 and x^0 satisfy on the interval $t_1 \le t$ t₂ the Hamiltonian system

$$\begin{vmatrix}
\dot{x}_i = \frac{\partial H(\overline{\psi}, x, u)}{\partial \varphi_i} \\
\dot{\psi}_i = -\frac{\partial H(\overline{\psi}, x, u)}{\partial x^i}
\end{vmatrix} \qquad i = 0, 1, \dots, n$$

and the condition of maximum

$$H(\overline{\psi}(t), x(t), u(t)) = M(\overline{\psi}(t), x(t)); \tag{8}$$

thereby M, x = 0, and ψ_0 = const < 0. It is noted that the principle of maximum holds also under more general assumptions than above Under certain conditions, the problem is equivalent to Lagrange's problem of variational calculus, whereby the principle of maximum coincides with Weierstrass's criterion. The basic difference between both formulations consists in the arbitrariness of the set .Q. (of the values of u) in the case of the principle of maximum. The optimum problem for the case of limited phase coordinates means Uard 4/6

30556 \$/569/61/002/000/002/008 D298/D302

Principle of maximum in the theory ...

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that only such allowed controllers can be chosen, for which the corresponding phase trajectory of (2) belongs entirely to a fixed, closed region G of n-dimensional phase space Xn. In this case the functional (3) is minimized. Further, a theorem is formulated for optimal trajectories which lie at the boundaries of the region G. In order to uniquely determine the optimum trajectory, a further condition has to be satisfied by the trajectory when it passes from the interior of G to its boundary; this condition is called discontinuity (jump) condition (as the covariant function $\overline{\psi}$ may undergo a discontinuity). Points of the boundary g(x) = 0, which satisfy certain conditions, are called point of contiguity (junction). A theorem is formulated which relates the discontinuity conditions to the points of contiguity. Further, a statistical problem is stated. The significance, for optimization theory, of the obtained result, has yet to be ascertained. It is noted, that it led already to the solution of a new problem "small parameter" for parabolic equations. The phase-coordinates are denoted by z. In addition, the point Q with probability distribution in the space R, is considered. It is required to select the controller u(t) of z so that the functional card 5/6

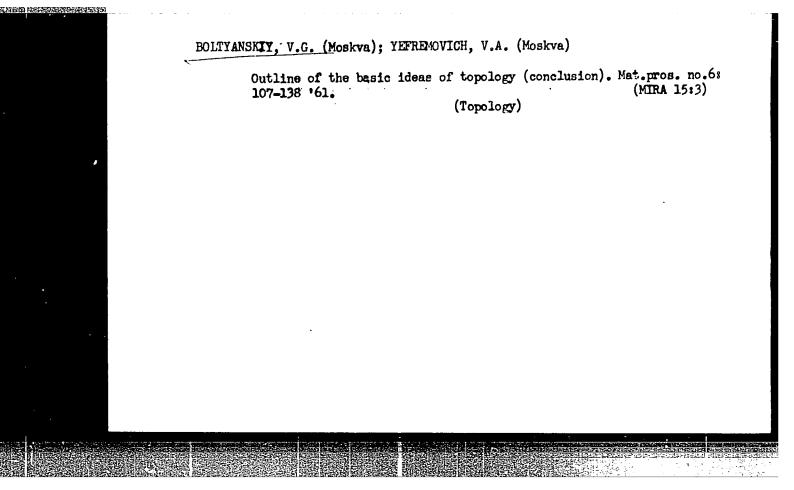
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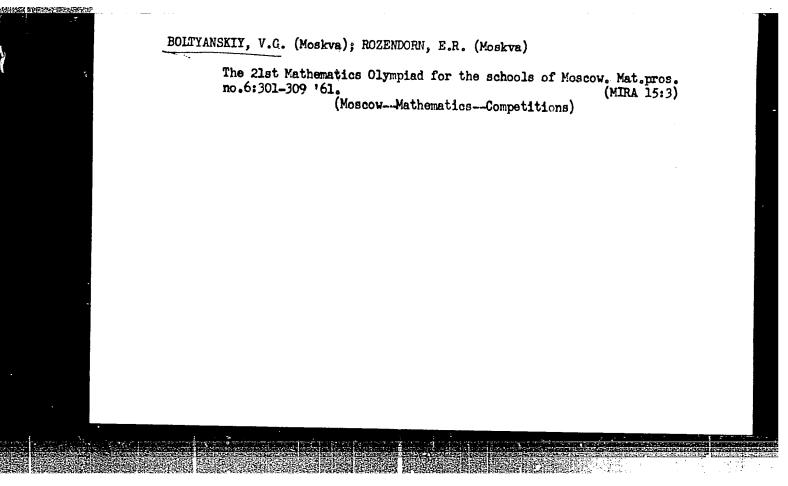
Principle of maximum in the theory ... S/569/61/002/000/002/008

$$\int_{0}^{\infty} h(\tau) \frac{\partial}{\partial \tau} \left[\Psi_{u}(x, \sigma, \tau) \right] d\tau$$
 (15)

is minimized. The author obtained an effective formula for calculating the probability function Ψ . A discussion followed, A.I. Lur'ye (USSR), Sun-Tsyan' (People's Republic of China) were taking part. There are to references: 14 Soviet-bloc and 4 non-Soviet-bloc The references to the English-language publications read as follows: R.E. Bellman, G.I. Glicksber, O.A. Gross, Some aspects of the mathematical theory of control provesses. U.S. Air Force Project RAND, control systems. Proc. Nat. Ac. Sci., V. 45, No. 4, 1958, 573 - 577 D.W. Bushaw, Experimental towing tank. Stevens Institute of Technology, Report N 469, Hoboken, N.Y., 1953.

Card 6/6





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29896 \$/517/61/060/000/002/009 B112/B125

AUTHOR:

Boltyanskiy, V. G.

TITLE:

Application of the theory of optimal processes to approxima-

tion problems of functions

SOURCE:

Akademiya nauk SSSR. Matematicheskiy institut. Trudy.

v. 60, 1961, 82 - 95

TEXT: The author considers the following "fundamental problem": For the

integral $\int_{a}^{b} F(x(t), y(t))dt$ (F(x,y) and y(t) are given continuous func-

tions), an extremal function x(t) is sought, which satisfies n Lipschitz conditions with a given constant $\alpha \geqslant 0$. The existence of a solution and

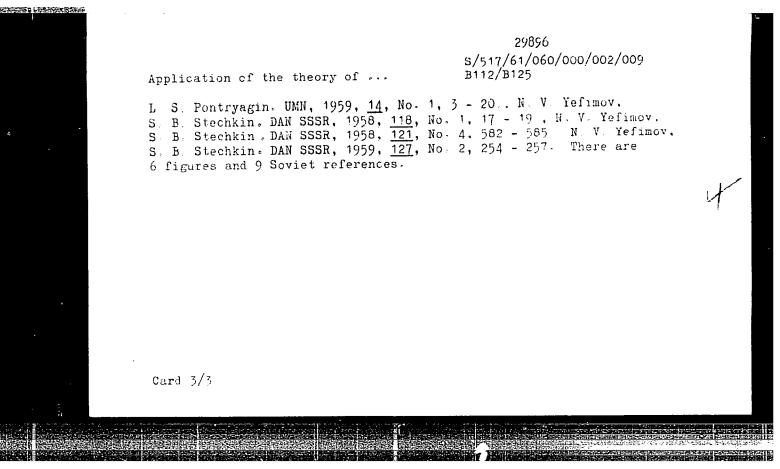
its uniqueness for the special case $F(x,y) = (x-y)^2$ are demonstrated. Then, the author reduces the fundamental problem to the following problem of the theory of optimal processes: A function u(t) ($|u(t)| \le a$) is sought, which has such a form that the system of differential equations $x^1 = x^2$, $x^2 = x^3$,..., $x^n = x^{n+1}$, $x^{n+1} = u(t)$ ($x^1 = x(t)$,..., $x^{n+1} = x^{n}$) (t)) Card 1/3

名[2] 医海绵中腺炎

Application of the theory of S/517/61/060/000/002/009 has a solution x^1 which is an extremal function of the integral $\int_{a}^{b} F(x^1, y(t)) dt$ for given boundary values $x^1(a)$ and $x^1(b)$ (i = 1.2,...,n+1). In order to solve this problem, the author applies some theorems of his (et al.) earlier paper "Teoriya optimal'nykh protsessov (Theory of optimal processes). I." (Izv. AN SSSR, ser. matem., 1960, 24.3 - 42). The principal result is the following: If x(t) is a solution of the fundamental problem, one of the relations $\int_{a}^{b} (\xi - t) \frac{\partial F(x(\xi), y(\xi))}{\partial x} d\xi = 0,$ $x^{n+1}(t) = \alpha \operatorname{sign} \left(\int_{a}^{b} (\xi - t)^{n} \frac{\partial F(x(\xi), y(\xi))}{\partial x} d\xi\right)$

will be fulfilled in the interval [a,b]. Several examples illustrate the theoretical part of this paper. The author refers to the following papers: V. G. Boltvanskiy, R. V. Gamkrelidze, L. S. Pontryagin. DAN SSSR, 1956.

110, No. 1, 7 - 10., V. G. Boltvanskiy, DAN SSSR, 1958, 119, No. 6, 10701073., R. V. Gamkrelidze. DAN SSSR, 1958, 123, No. 2, 223 - 226.,
Card 2/3



"APPROVED FOR RELEASE: 06/09/2000

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16.4000 (1031, 1121, 1344)

25772 S/020/61/139/002/002/017 0111/0333

AUTHOR 8

Boltyanskiy, V. G.

TITLE:

Modelling of optimal linear highspeed operations by

means of relay circuits

PERIODICAL: Akademiya nauk SSSR. Doklady, v. 139, no. 2, 1961,

TEXT: The author considers an object with the equations of motion

$$\dot{x}^{i} = \sum_{k=1}^{n} a_{ik}^{i} x^{k} + \sum_{g=1}^{r} b_{g}^{i} u^{g}, i = 1, \dots, n, (1)$$

where the control variable $u=(u^1,\ldots,u^r)$ is a point of the convex closed bounded polyhedron U in the space E^r with the coordinates u^1 , ..., u^r . Find an $u(t) \in U$ so that the system comes from the position x_0 into the position x_1 within shortest times.

In vector form (:) has the form

Card 1/7

where A : X \rightarrow X (X-- phase space(x¹, ..., xⁿ)) and B : E^r \rightarrow X are linear operators defined in the coordinates x¹, ..., xⁿ and u¹, ..., u^r by the matrices (a_i) and (b_k).

Let the following condition be satisfied: If the vector w is paral i with one of the edges of U, then the vectors Bw, ABw, ..., Aud Bw are linearly independent in X.

The author introduces the auxiliary system

$$\dot{\Psi} = -\Lambda^* \Psi, \qquad (3)$$

where the operator A^{\bigstar} is described by the matrix transposed to (a_j^i) . For an arbitrary vector $\Psi = (\Psi_1, \dots, \Psi_n)$ assume that $e(\Psi)$ denotes the set of all $u \in U$ for which

25772 S/020/61/139/002/002/017 Modelling of optimal linear . . . C111/C333

$$(\Psi, Bu) = \sum_{\alpha=1}^{n} \sum_{q=1}^{r} \Psi_{\alpha} b_{q}^{\alpha} u^{q}$$
(4)

as function of u & U attains its maximum.

Theorem 1: For an arbitrary nontrivial solution $\Psi(t)$ of (3) the set $e(\Psi(t))$ is a corner of the polyhedron U for all values t except a finite number. I. e. the relation

$$u(t) = e(\Psi(t)) \tag{5}$$

(which is meaningless in a finite number of points) defines a piecewise constant function u(t) with values in the corners of U. Such functions are denoted as extremal controls.

Theorem 2: Every optimal control is extremal. Conversely, assume that the origin of $\mathbf{E}^{\mathbf{r}}$ is an interior point of U and that all eigen values Card 3/7

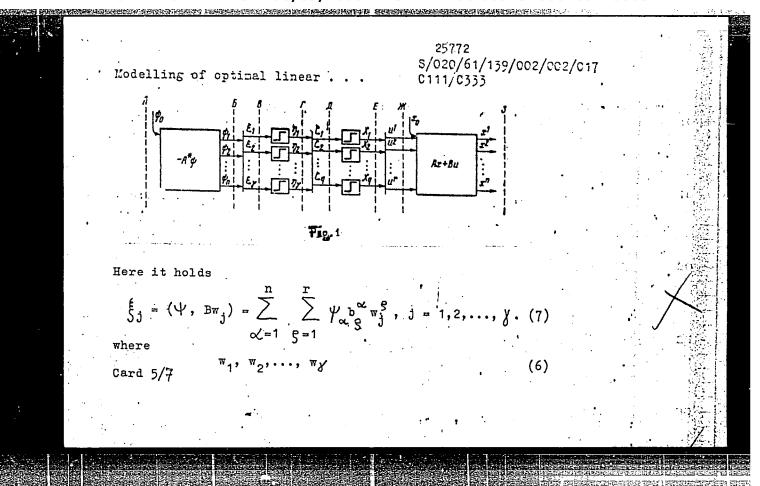
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Modelling of optimal linear . . .

of (a_j^1) possess negative real parts. Then, for every point $x_0 \in X$, there exists one and only one (up to time translation) extremal control u(t) transferring the phase point from the position x_0 into the origin θ of the space X. This extremal control is simultaneously optimal.

The extremal trajectory is uniquely determined by the choice of the initial value Ψ_0 . The author proposes a modelling plant which allows to determine the corresponding extremal trajectory x(t) for given Ψ_0 . Figure 1 shows the scheme of the plant.

Card 4/7



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Modelling of optimal linear . . . C111/C333 are vectors parallel with the edges of U, w_j^1, \ldots, w_j^r are the components of w_j . Furthermore $\eta_j = \operatorname{sgn} \xi_j$. Then

$$S_{i} = I_{i} - I + \sum_{j} \varepsilon_{ij} \gamma_{j}$$
 (8)

where $\mathcal{E}_{ij} = 1$ or = -1, if the vector \mathbf{w}_j or \mathbf{w}_j beginning in the corner \mathbf{e}_i of U lies in one of the edges of U; otherwise, \mathcal{E}_{ij} is not defined and is not considered. Then \mathcal{E}_{ij} \mathbf{w}_j are in the direction of the edges beginning in the corner \mathbf{e}_i ; the number of these edges is \mathbf{l}_i . Finally we have

$$u^{S} = \frac{1}{2} \sum_{\alpha=1}^{q} (1-\chi_{\alpha}) e_{\alpha}^{S}, \quad S = 1, ..., r$$
 (9)

where e_i^1, \ldots, e_i^r are the coordinates of the corner e_i of v and q is Card 6/7

the number of corners.

Theorem 3: The scheme shown on figure ! (see also (7), (8), (9) realizes a motion of the object (2) along the extremal trajectory (for arbitrary initial values of the variables Ψ_i and x^i).

A simpler scheme is obtained in the case where U is a rectangular parallelepiped so that the u in (1) are independent from each other.

L. S. Pontryagin and R. V. Gamkrelidze are mentioned. There are 2 figures and 5 Soviet-bloc references.

ASSOCIATION: Matematicheskiy i Stitut imeni V. A. Steklova Akademii nauk SSSR (Institute of Mathematics imeni V. A. Steklov of the Academy of Sciences USSR)

PRESENTED: March 11. 1961, by L. S. Pontryagin, Academician

SUBMITTED: March 9. 1961

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29108 \$/020/61/140/005/003/022 C111/C222

AUTHOR:

Boltyanskiy, V. G.

TITLE:

Sufficient conditions for optimality

PERIODICAL: Akademiya nauk SSSR. Doklady, v. 140, no. 5, 1961,

TEXT: The author gives sufficient conditions for the optimality of a process on the base of the dynamic programming by Bellman as well as on the base of the maximum principle by Pontryagin whereby a connection between these two methods is found.

In the phase space X of the variable $x = (x^1, x^2, ..., x^n)$ the author considers

$$\dot{x}^{i} = f^{i}(x^{1}, ..., x^{n}, u), i = 1,..., n.$$
 (1)

The piecewise continuous control u(t), $t \le t \le t_1$, with values in a topological space U is called admissible with respect to $x \in V \subseteq X$ if for a substitution of u into (1) the solution of (1) with the initial value $x(t_0) = x_0$ for $t_0 \le t \le t_1$ lies in V. Let the f^1 and $\partial f^1/\partial x^1$ be continuous on $V \times U$.

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4

29108 S/020/01/140/005/003/022 C111/C222

Sufficient conditions for optimality

Problem: Among the admissible u = u(t) that one shall be determined which transfers the phase point from the position x in a given other position x_1 in the shortest time (optimal control).

Let K be a bounded closed s-dimensional (s#n) convex polyhedron in the space of the variables $\xi = (\xi^1, \xi^2, \dots, \xi^8)$. On an open set N of \mathbb{R}^2 containing K let be given a differentiable mapping $\mathfrak{P}: \mathbb{N} \to \mathbb{X}$ so that the functional matrix $(\partial x^1/\partial \xi^1)$ in every $\xi \in \mathbb{K}$ has the rank s and that to different points of K there correspond different points of X. The image $L = \mathfrak{P}(\mathbb{K})$ of K is called a curvilinear s-dimensional polyhedron in X. Every set $\mathbb{M} \subseteq \mathbb{V}$ being representable as a union of an at most countable number of curvilinear polyhedra of the dimensions \approx n is called a piecewise smooth set in V if these polyhedra lie so that in every closed bounded set in V there intersect at most a countable set of these polyhedra

Theorem I: Let a \in V be a fixed point. In V let be given a real continuous function $\omega(x)$ so that a) $\omega(a) = 0$, $\omega(x) < 0$ for $x \neq a$; b) in V there exists a piecewise smooth set M so that $\omega(x)$ on $V \setminus M$ is

Card 2/5

29108

Sufficient conditions for optimality $\frac{5}{020/61/140/005/003/022}$ continuously differentiable with respect to x^1, x^2, \dots, x^n , and satisfies the condition

$$\sup_{u \in U} \sum_{\infty}^{n} \frac{\partial \omega(x)}{\partial x^{\infty}} f^{\infty}(x, u) = 1 \quad \text{for } x \in V \setminus M . (2)$$

Then for every $\mathbf{x}_0 \in \mathbf{V}$ and every control admissible with respect to \mathbf{x}_0 which transfers the phase space from the position \mathbf{x}_0 into the position \mathbf{a}_0 , the time of transferring from \mathbf{x}_0 to a is not smaller than $-\omega(\mathbf{x}_0)$.

Theorem 2: Theorem 1 is valid also then if instead of the piecewise smoothness of M it is demanded: M is closed in V and contains no inner points; besides, $\omega(x)$ satisfies locally the Lipschitz condition (in the neighborhood of each $x\in V$).

Conclusion: If the assumptions of theorem 1 (or theorem 2) are satisfied and for every $x \in V$ there exists a control admissible with respect to x_0 which transforms x_0 to a in the time $-c_0(x_0)$ then all these Card 3/5

29108 S/020/61/140/005/003/022 C111/C222

Sufficient conditions for optimality controls are optimal.

Theorem 3 is devoted to the maximum principle. Let

$$P^{0} \subset P^{1} \subset P^{2} \subset \ldots \subset P^{n-1} \subset P^{n} = V$$
 (3)

where all P^i are piecewise smooth; let v(x) be a function with values in U given in V. Under numerous assumptions on the structure of the sets P^i and on the course of the trajectories of

$$x^{i} = f^{i}(x^{1}, \dots, x^{n}, \nu(x)),$$

$$i = 1, \dots, n$$
(4)

with the aid of the sets (3) and the function v(x) the author introduces the notion of the regular synthesis for (1) in V. Then it is proved that certain trajectories appearing in the definition of the regular synthesis which satisfy the maximum principle are really optimal (theorem 3).

There are ? Soviet-bloc and 1 non-Soviet-bloc reference. The reference Card 4/5

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Sufficient conditions for optimality

to the English-language publication reads as follows: R. Bellman, Dinamicheskoye programmirovamiye (Dynamic programming). JL, 1960

ASSOCIATION: Matematicheskiy institut imeni V. A. Steklova Akademii nauk SSSR (Mathematical Institute imeni V. A. Steklov of

the Academy of Sciences USSR)

PRESENTED:

May 19, 1961, by L. S. Pontryagin, Academician

SUBMITTED:

May 17, 1961

Card 5/5

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